## **Final Review**

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#### Final logistics

- 100 minutes (half an hour longer than quiz1&2)
  - Cover all materials
  - More emphasis on the second half of class (70%)
- Closed book
  - except for one double-sided cheat sheet
  - No electronic devices
- Read all questions, do the easier ones first.

Disclaimer: this review is not complete.

Not all exam materials are covered by this review!

# What we've learnt (first half)

#### 1. Clanguage

- pointers, bitwise operations
- Compilation, linking

#### 2. Basic program execution

- Digital representation of numbers and characters
- CPU state vs. memory, basic x86 instructions
- Buffer overflow

# What we've learnt (second half)

- 3. Dynamic Memory Allocation
- 4. Advanced program execution
  - virtual memory
  - caching
  - Multi-processing
- 5. Multi-threading

# Topic #1 C programming

## Global vs. Local vs. Heap Variable

- Know the whereabouts of variables, when they are allocated/deallocated
- Variables are not automatically initialized upon declaration

```
void add(int x) {
    x++;
}

void main() {
    int x = 0;
    add(x);
    printf("x is %d\n", x);
}
```

What's the output?

Answer: 0

# Global vs. Local vs. Heap Variable

- Know the whereabouts of variables, when they are allocated/deallocated
- Variables are not automatically initialized upon declaration

```
int add(int x) {
    x++;
    return x;
}

void main() {
    int x = 0;
    x = add(x);
    printf("x is %d\n", x);
}
```

What's the output?

Answer: 1

## Global vs. Local vs. Heap Variable

- Know the whereabouts of variables, when they are allocated/deallocated
- Variables are not automatically initialized upon declaration

```
int add(int x) {
    x++;
    return x;
}

void main() {
    int x = 0,
    x = add(x);
    printf("x is %d\n", x);
}
```

What's the output?

Answer: Could be any number

#### **Pointers**

- Pointers are addresses to variables
- You must be aware of whether the variable being pointed to has been allocated or not and where

```
void add(int *x) {
  (*x) = (*x) + 1;
}

void main() {
  int y = 0;
  int *x = &y;
  add(x);
  printf("x is %d\n", *x);
}
```

What's the output?

Answer: 1

#### **Pointers**

- Pointers are addresses to variables
- You must be aware of whether the variable being pointed to has been allocated or not, and where

```
void add(int *x) {
    (*x) = (*x) + 1;
}

void main() {
    int y = 0;
    int *x = &y;
    add(x);
    printf("x is %d\n", *x);
}
```

What's the output?

Answer: Likely segmentation fault

# #1.2 C Programming

- Pointers are ddresses to variables
- You must be aware of whether the variable being pointed to has been allocated or not, and where

```
int *
sum(int x, int y) {
   int z = x + y;
   return &z;
}

void main() {
   int *r1 = sum(1,1);
   int *r2 = sum(*r1, 1);
   printf("%d\n", *r2);
}
```

What's the output?

Answer: likely
garbage

#### Pointers and arrays

Arrays store a set of identically typed elements contiguously

```
void main() {
   int nums[5] = {1, 2, 3, 4, 5};
   int *p;
   p = nums + 2; // equivalent to p = &nums[2];
   p++;
   printf("%d\n", *p);
}
```

What's the output?

Answer: 4

# Little vs. Big Endian

```
void main() {
  int x = 1<<31;    // equivalent to x = 0x80000000;
  char *y;
  y = (char *)&x;
  for (int i = 0; i < 4; i++) {
     printf("%d ", y[i]);
  }
}</pre>
```

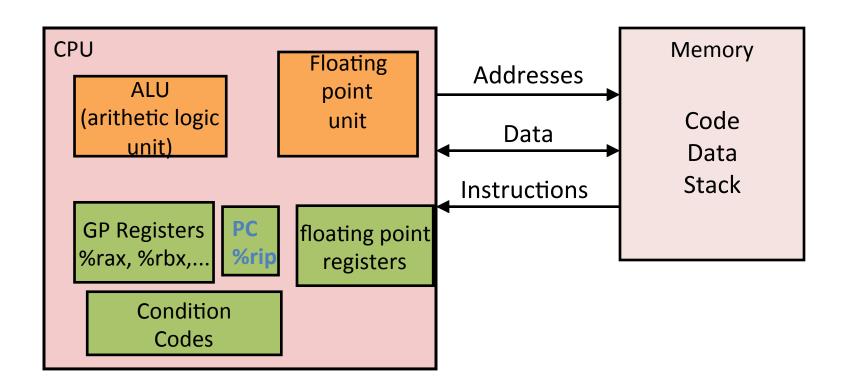


#### C: Other Concepts

- ASCII characters
- C string
  - Null-terminated ASCII character array
- Use malloc appropriately
  - allocate the right size
  - free allocated memory to avoid memory leak

# Topic #2 Basic Program Execution

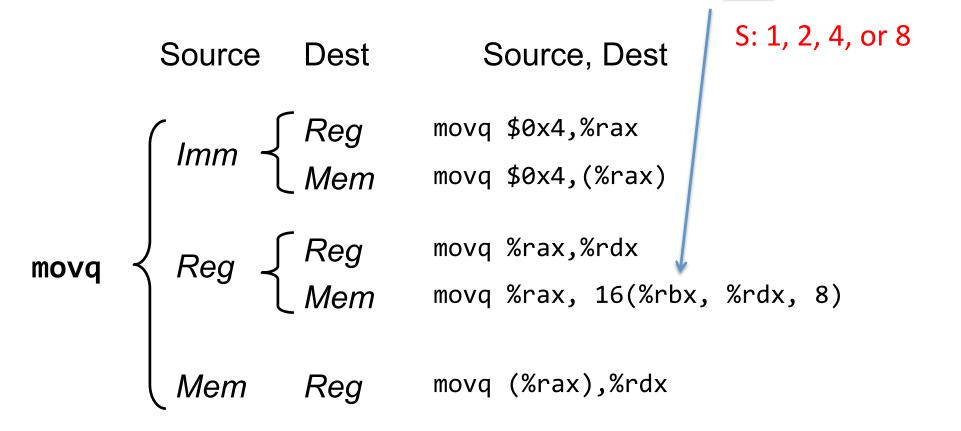
# **Basic Program Execution**



#### Machine instructions: mov

#### 1. mov instructions

general memory addressing mode: D(Rb, Ri, S): val(Rb) + S\*val(Ri) +D



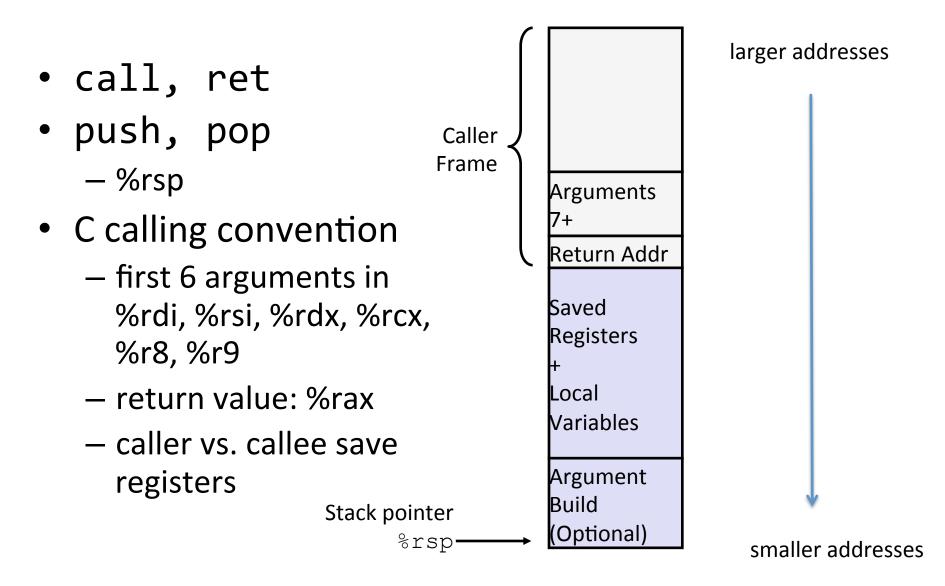
#### Machine instructions

- Arithmetic operations
  - add %eax, %ebx
  - sub, mul
- The lea instruction
  - lea 0x1(%rax, %rbx, 2), %rdx
- Bitwise-operations:
  - shl/shr, sal/saq, and, or, xor

#### **Control flow**

- Normal control flow is linear
  - load instruction stored at address %rip
  - execute it
  - %rip = %rip + (length of instruction)
- Non-linear Control flow
  - combination of two types of instructions
    - instructions that set conditional codes, CF, ZF, SF, OF
    - jmp instructions that may or may not jump depending on condition codes
  - condition codes can be set
    - implicitly: add, sub ..
    - explicitly: cmp, test, ...

#### Procedure execution



#### **Buffer Overflow**

#### Before call to gets

Stack Frame for call echo

**Return Address** (8 bytes)

20 bytes unused

```
[3] [2] [1] [0] buf ← %rsp
```

```
void echo()
    char buf[4];
    gets(buf);
    puts(buf);
```

```
echo:
  subq $24, %rsp
 movq %rsp, %rdi
  call gets
```

# Topic #3 Dynamic Memory Allocation

## Dynamic memory allocation

- How to implement malloc/free?
- Goal: high throughput and high utilization
- Design questions:
  - how to keep track of free blocks
  - which free blocks to allocate?
  - free is only given a pointer, how to know its block size?

## Dynamic memory allocation

- implicit list
  - one (implicit) list containing all free and non-free blocks
- explicit free list
  - one explicit linked list containing all free blocks
- segregated free list
  - multiple explicitly linked lists for free blocks,
  - each links corresponds to a different size class

```
typedef struct {
                           unsigned long size_and_status;
chunk size 0
                           unsigned long padding;
              header
                        } header;
 8B padding
              (16 bytes)
                         bool get_status(header *h) {
Payload
                            return h->size_and_status & 0x1L;
                         size_t get_chunksize(header *h) {
chunk size 0
                            return h->size_and_status& ~(0x1L);
              footer
8B padding
              (16 bytes) }
```

Question: given pointer p of type void \* pointing to the payload, how to get a pointer to the current, next, previous block?

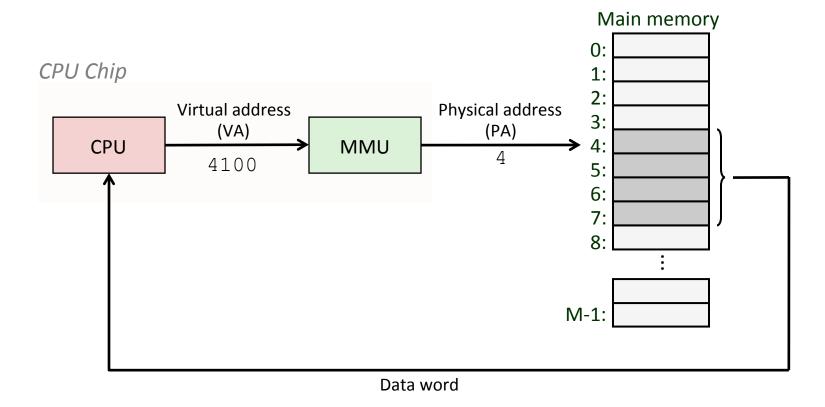
```
curr = (header *)((char *) p - sizeof(header));
next = (header *)((char *)p + sizeof(header) + get_chunksize(curr));
footer = (header *)((char *)p - 2*sizeof(header));
prev = (header *)((char *)p - 3*sizeof(header)-get_chunksize(footer));
```

# Topic #4 Advanced topics on program execution

VM, Caching, Multiprocessing

#### Virtual memory

- User program access virtual address
- 32-bit address → address range [0x00000000, 0xffffffff]

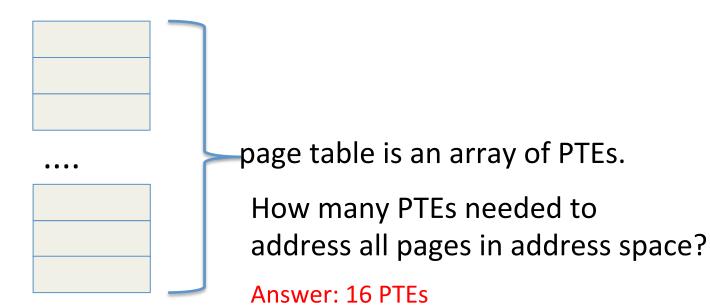


#### VM: one-level page table

- Example:
  - 8-bit virtual and physical addresses
  - 16-byte page size

How many pages in the 8-bit address space?

Answer:  $2^8/16 = 2^4 = 16$  pages



#### VM: one-level page table

- Example:
  - 8-bit virtual and physical addresses
  - 16-byte page size

ptable[1]:

ptable[0]:

VA: 0x11010010 PTE is 1-byte size ptable[15]: 0xA1 What's the PA? ptable[14]: 0xB1 Answer: page fault ptable[13]: 0xC0 VA: PPN validity bit ptable[2]: 0xD00x11100010

0xF1

0xE0

Answer: 0xB2

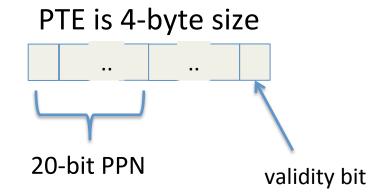
What's the PA?

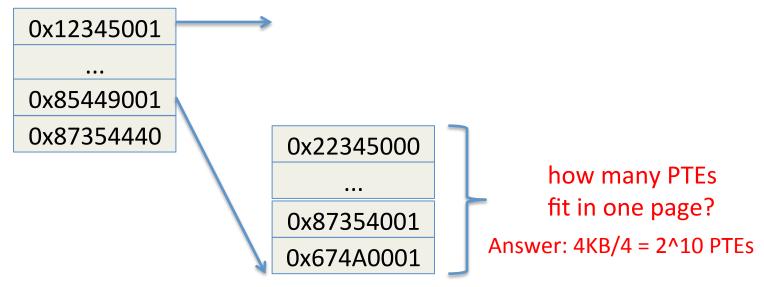
#### VM: Multi-level page table

- Example:
  - 32-bit virtual and physical addresses
  - 4KB page size

How many pages in the 32-bit address space?

Answer: 2^32/4KB = 2^20 pages

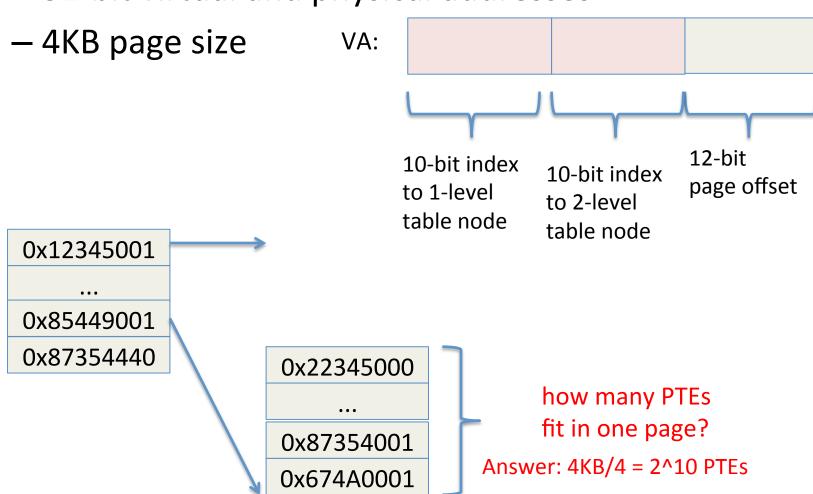




## VM: Multi-level page table

#### Example:

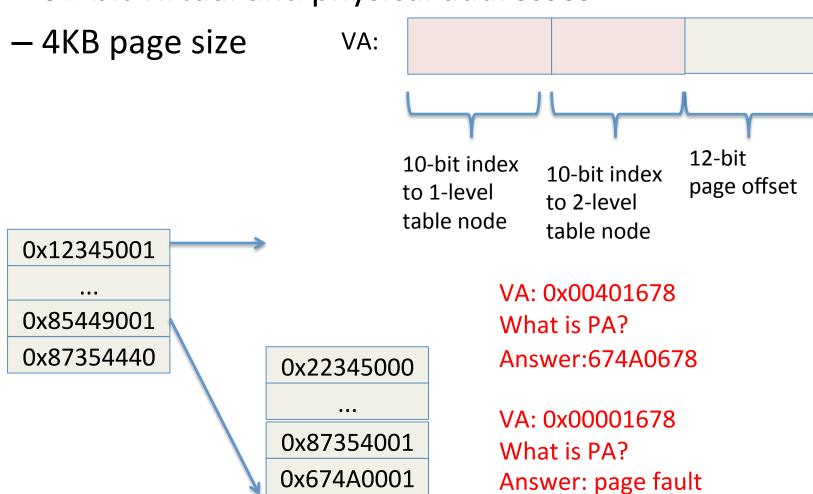
32-bit virtual and physical addresses



## VM: Multi-level page table

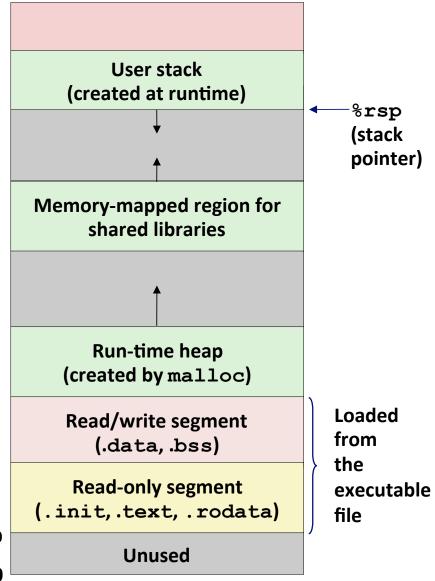
#### Example:

32-bit virtual and physical addresses



## Address space

 Each running program has its own page table and address space



0x400000

#### OS and user-level processes

- OS: a layer of software between app and h/w
  - hide h/w details
  - manage resource sharing among apps
- H/w primitive: privileged vs. unprivileged execution
  - exception (e.g. page fault)
  - traps (used for syscall)
  - interrupt (e.g. timer interrupt)

# invoking kernel functions: syscalls

- h/w instruction, syscall
  - open, close, read, write
  - futex, fork, clone
  - man 2 fork

# OS abstraction: Multi-processing

- Process: an instance of a running program
- Managed by OS, each process has
  - its own virtual address space
  - saved execution context
  - process id

<del>--</del> ....

#### fork and exec

```
void main() {
    printf("hello\n");
    if (fork() == 0) {
        printf("big\n");
        exec("/bin/echo", "world");
        printf("lovely\n");
      }
    }
    printf("Bye\n");
```

What are potential interleavings?

```
print "bye"

print "hello" 

print "big" 

exec "/bin/echo" "world
```

hello hello hello big big bye bye world big world bye world

# forked processes have separate address space

```
int global = 1;
void main() {
    pid_t pid = fork();
    if (pid == 0) {
        global = 2;
        printf("child global=%d\n", global);
    } else {
        waitpid(pid,...)
        printf("parent global=%d\n", global);
    }
}
```

What are possible outputs?

```
child global=2 parent global=1
```

# Topic #5 Multi-threaded programming

## Concurrent programming

- A single process can have multiple threads
  - each thread has its own control flow & stack
  - all threads share the same address space
- Multi-threaded programs need synchronization
- Synchronization problems:
  - races
  - deadlock

#### Races

- Examples:
  - modifying shared counters
  - modifying shared linked list, hash table etc.
- Caused by arbitrary interleaving of execution among different threads

```
Thread-1 (x++)

read x (from memory) into %eax

add $1, %eax

write %eax to x (in memory)

write %eax to x
```

#### Races

```
node *head;
list_insert(int x) {
   L1: node *n = malloc ...
   L2: n->val = x;
   L3: n->next = head;
   L4: head =n;
}
```

#### what can go wrong if two threads insert at the same time?

```
Thread-1: list_insert(1)

L1
L2

L3

L3

L4
```

#### Mutexes

Protect "critical section"

#### Big lock implementation

```
int acc[100];
pthread_mutex_t mu;
void transfer(int x, int y){
   pthread_mutex_lock(&mu);
   acc[x] -=10;
   acc[y] += 10;
   pthread_mutex_unlock(&mu);
}
```

#### Fine-grained lock

```
typedef struct {
  int balance;
  pthread mutex t mu;
}account t;
account t acc[100];
void transfer(int x, int y) {
pthread mutex lock(&acc[x].mu);
pthread mutex lock(&acc[y].mu);
acc[x].bal == 10;
acc[y].bal += 10;
pthread mutex unlock(&acc[x].mu);
pthread_mutex_unlock(&acc[y].mu);
```

#### Conditional variables

- lets a thread wait for some condition to become true
- Remember the pattern for using conditional variables

# Thread-1 mutex\_lock(&m) while (condition != true) cond\_wait(&c, &m); //condition is true modify shared state mutex\_unlock(&m)

#### Thread-2

```
mutex_lock(&m);

condition = true;
cond_signal(&c);
//or cond_broadcast(&c)

mutex_unlock(&m);
```

# H/W Atomic instructions

Basic spinlock implementation

```
spin_lock(int *m)
{
    while (xchg(m, 1)!= 0);
}

spin_unlock(int *m)
{
    xchg(m, 0);
}
```