

Machine Program: Procedure

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Slides based on Tiger Wang

Roadmap: how does hardware execute a program?

- Where is data stored?
 - Instructions and (most) data are stored in memory
 - Temporary data (e.g. local variables, loop variables) stored in registers
- How does CPU execute a program?
 - Load an instruction from memory according to PC
 - Execute instruction (may access memory)
 - update PC
 - Repeat
- Modes of execution:
 - sequential:
 - PC is changed to point to the next instruction
 - control flow: jmp, conditional jmp
 - PC is changed to point to the jump target address
 - **Today → procedure call**

Requirements of procedure calls?

```
P(...) {  
  y = Q(x);  
  y++;  
}
```

```
int Q(int i)  
{  
  int t, z;  
  ...  
  return z;  
}
```

1. Passing control



Requirements of procedure calls?

```
P(...) {  
  y = Q(x);  
  y++;  
}
```

```
int Q(int i)  
{  
  int t, z;  
  ...  
  return z;  
}
```

1. Passing control
2. Passing Arguments & return value

Requirements of procedure calls?

```
P(...) {  
  y = Q(x);  
  y++;  
}
```

```
int Q(int i)  
{  
  int t, z;  
  ...  
  return z;  
}
```

1. Passing control
2. Passing Arguments & return value
3. Allocate / deallocate local variables

How to transfer control for procedure calls?

```
void main(){  
    ..  
    f(..)  
L1: ..  
}
```

```
void f(){  
    ..  
    g(..)  
L2: ..  
}
```

```
void g(){  
    ..  
    h(..)  
L3: ..  
}
```

How to transfer control for procedure calls?

```
void main(){  
    ..  
    f(..)  
L1: ..  
}
```

```
void f(){  
    ..  
    g(..)  
L2: ..  
}
```

```
void g(){  
    ..  
    h(..)  
L3: ..  
}
```

Jump to f()
Remember where to come back

L1

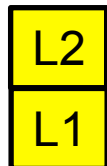
How to transfer control for procedure calls?

```
void main(){  
  ..  
  f(..)  
L1: ..  
}
```

Jump to f()
Remember where to come back

```
void f(){  
  ..  
  g(..)  
L2: ..  
}
```

Jump to g()
Remember where to come back



```
void g(){  
  ..  
  h(..)  
L3: ..  
}
```


How to transfer control for procedure calls?

```
void main(){  
  ..  
  f(..)  
L1: ..  
}
```

Jump to f()
Remember where to come back

```
void f(){  
  ..  
  g(..)  
L2: ..  
}
```

Jump to g()
Remember where to come back

```
void g(){  
  ..  
  h(..)  
L3: ..  
}
```

Jump to h()
Remember where to come back



How to transfer control for procedure calls?

```
void main(){  
  ..  
  f(..)  
L1: ..  
}
```

```
void f(){  
  ..  
  g(..)  
L2: ..  
}
```

```
void g(){  
  ..  
  h(..)  
L3: ..  
}
```

Jump to f()
Remember where to come back

Jump to g()
Remember where to come back

Jump to L3
Forget L3



How to transfer control for procedure calls?

```
void main(){  
  ..  
  f(..)  
L1: ..  
}
```

```
void f(){  
  ..  
  g(..)  
L2: ..  
}
```

```
void g(){  
  ..  
  h(..)  
L3: ..  
}
```

Jump to f()
Remember where to come back

Jump to L2
Forget L2

Jump to L3
Forget L3



How to transfer control for procedure calls?

```
void main(){  
  ..  
  f(..)  
  L1: ..  
}
```

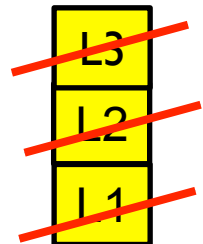
Jump to L1
Forget L1

```
void f(){  
  ..  
  g(..)  
  L2: ..  
}
```

Jump to L2
Forget L2

```
void g(){  
  ..  
  h(..)  
  L3: ..  
}
```

Jump to L3
Forget L3



How to transfer control for procedure calls?

```
void main(){  
  ..  
  f(..)  
L1: ..  
}
```

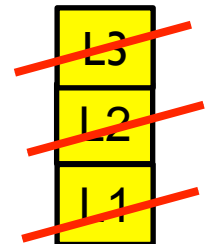
Jump to L1
Forget L1

```
void f(){  
  ..  
  g(..)  
L2: ..  
}
```

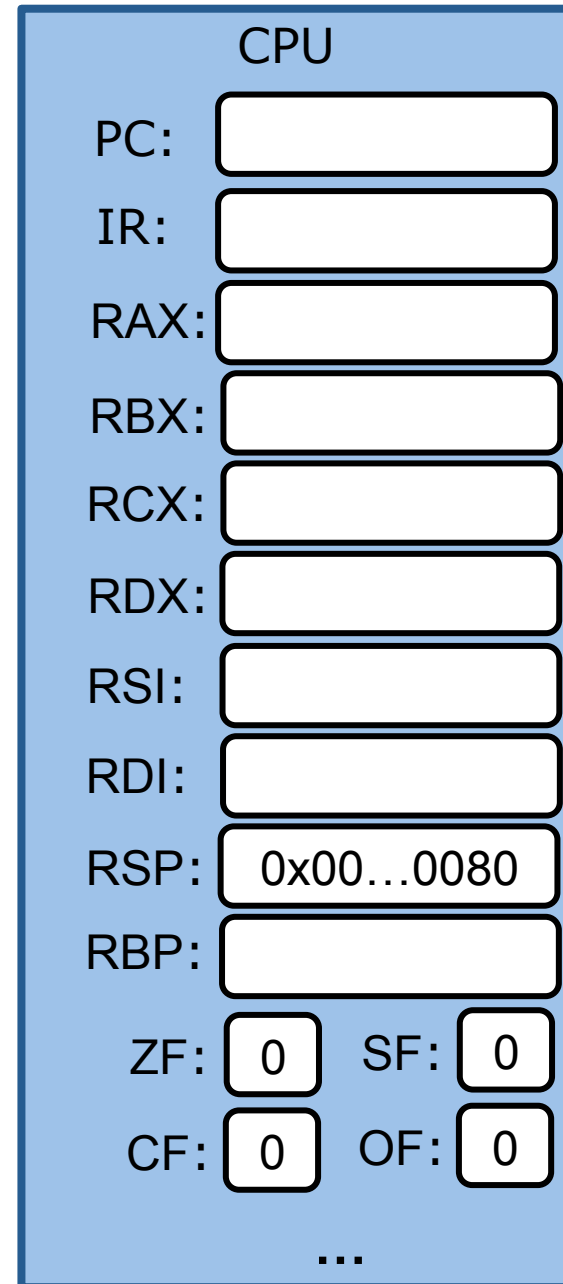
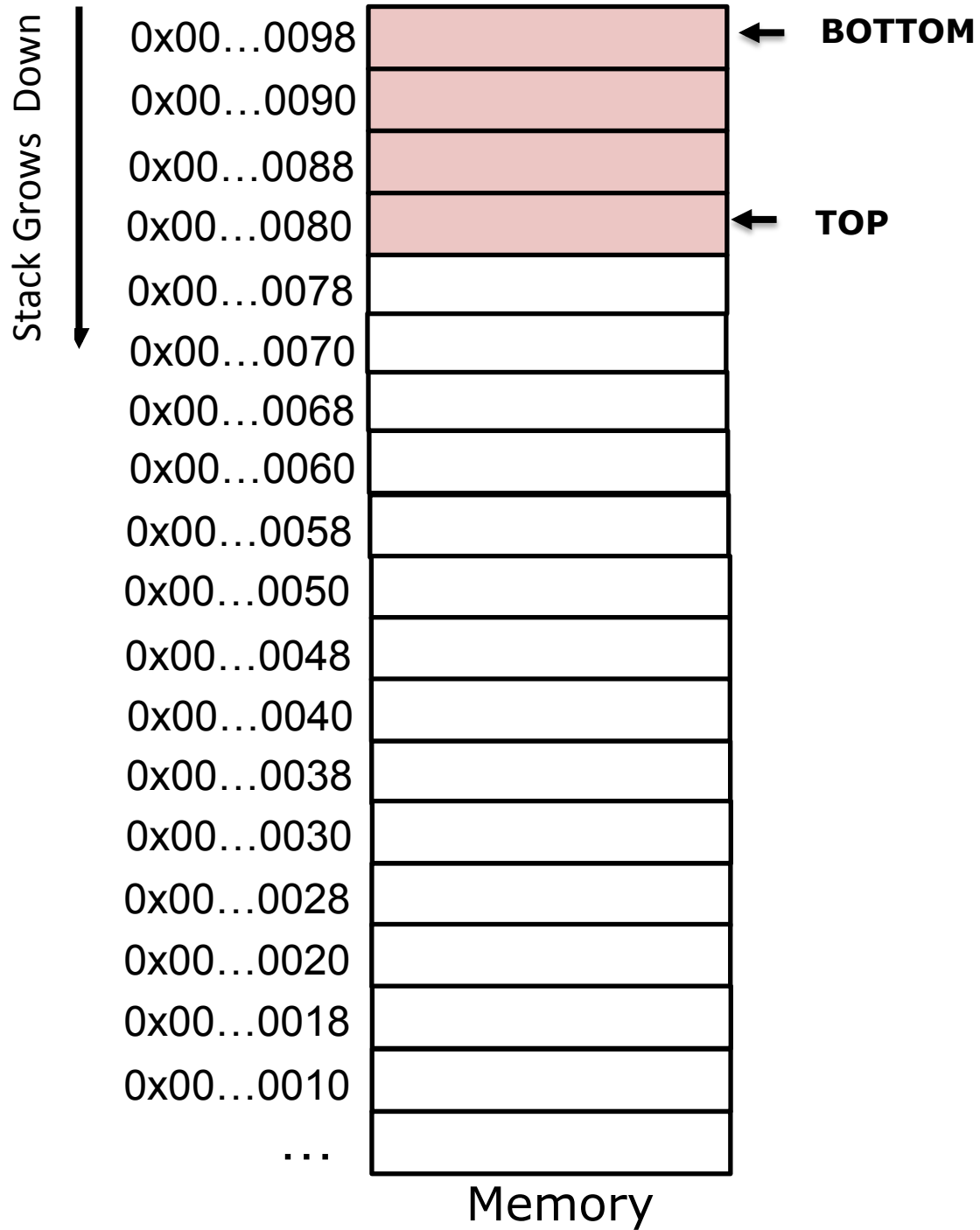
Jump to L2
Forget L2

```
void g(){  
  ..  
  h(..)  
L3: ..  
}
```

Jump to L3
Forget L3



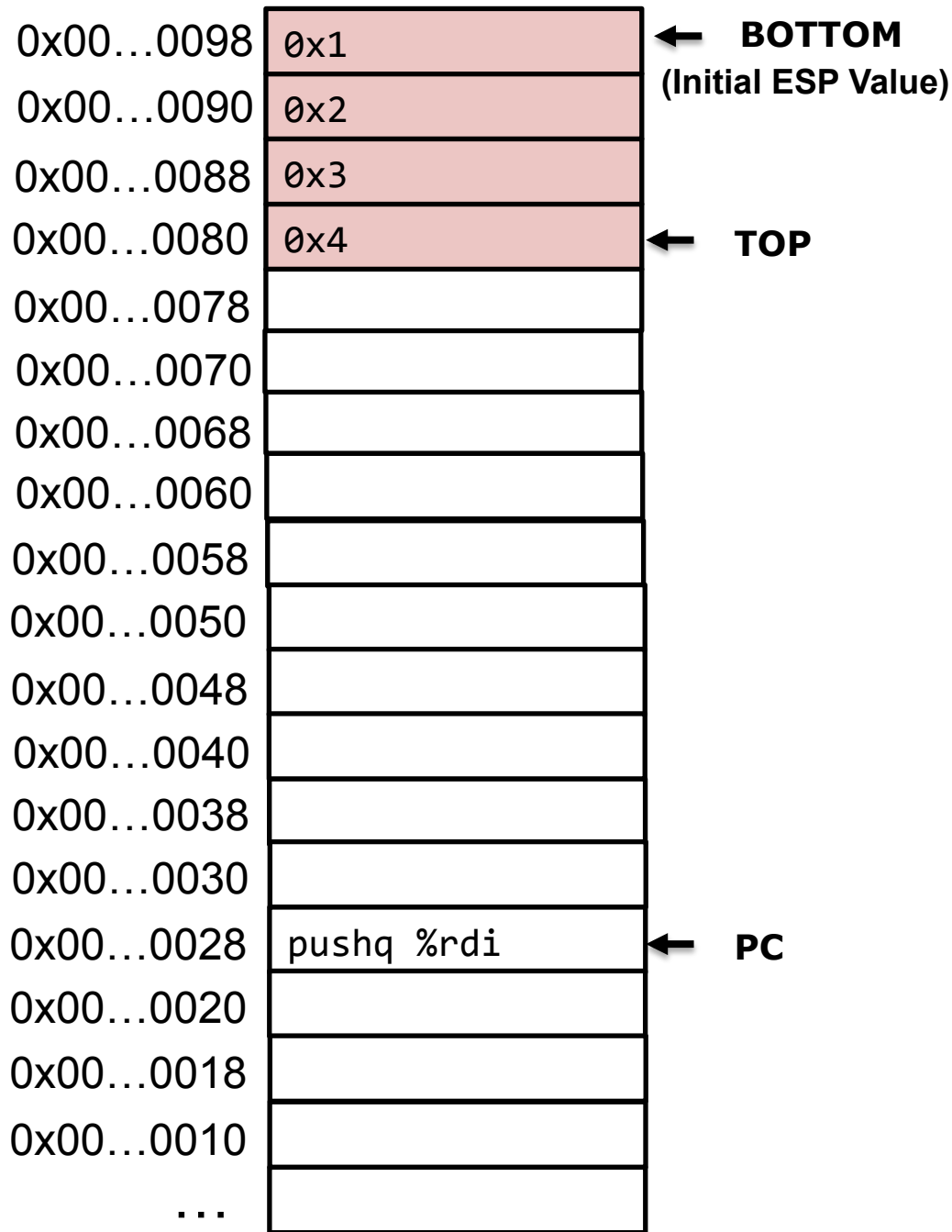
Stack



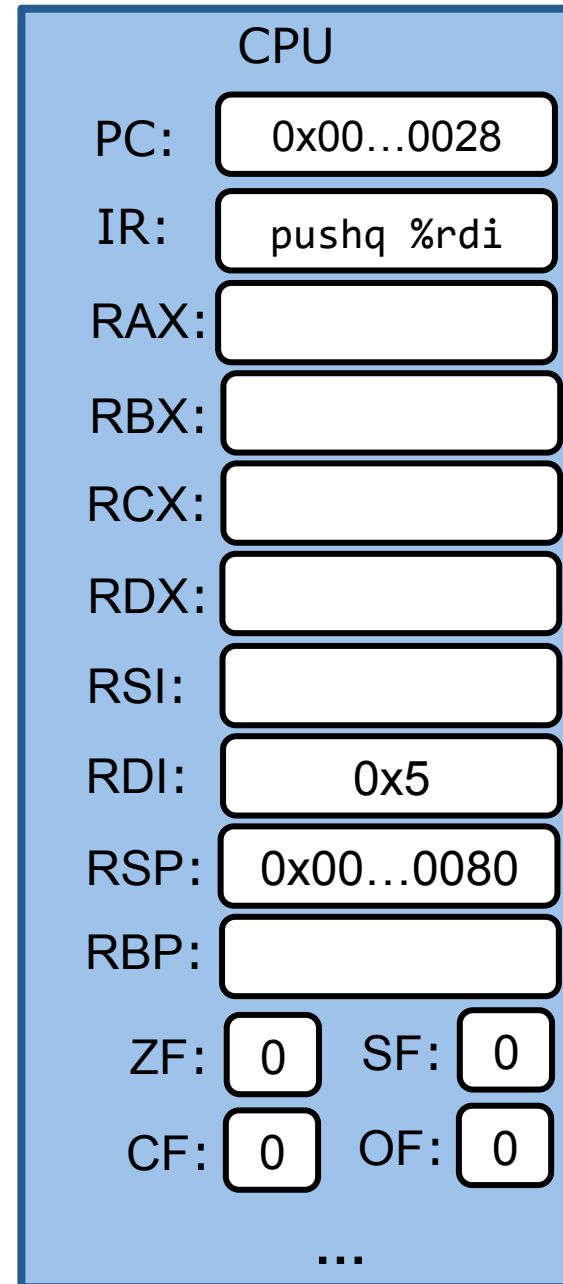
Stack – push Instruction

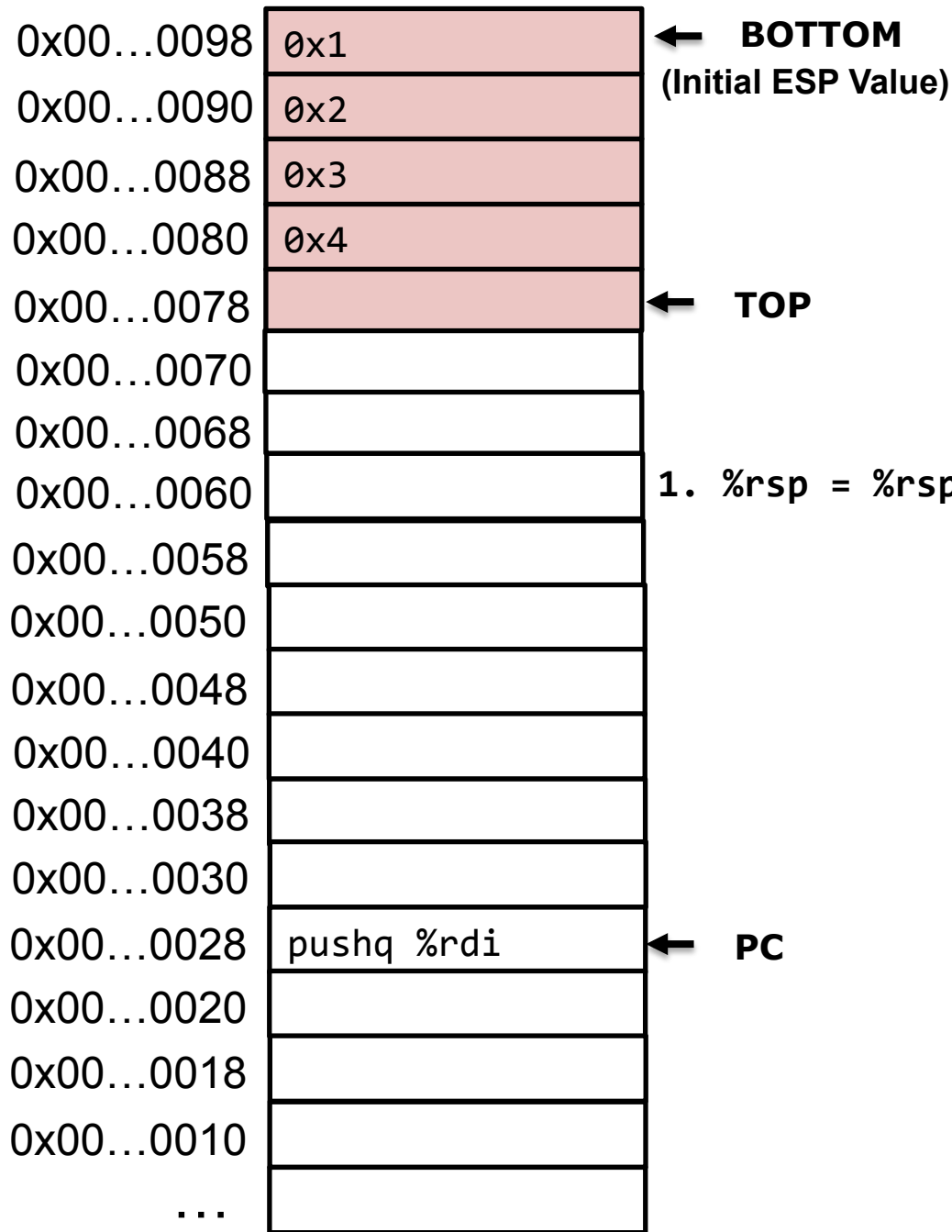
pushq src

- Decrement %rsp by 8
- Write operand at address given by %rsp

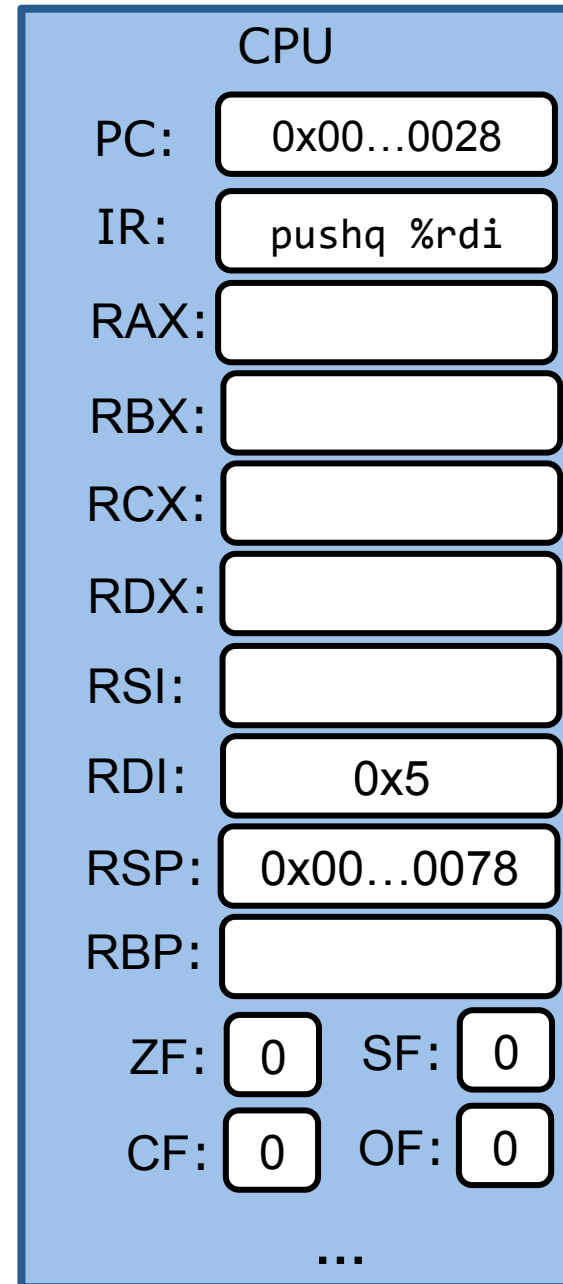


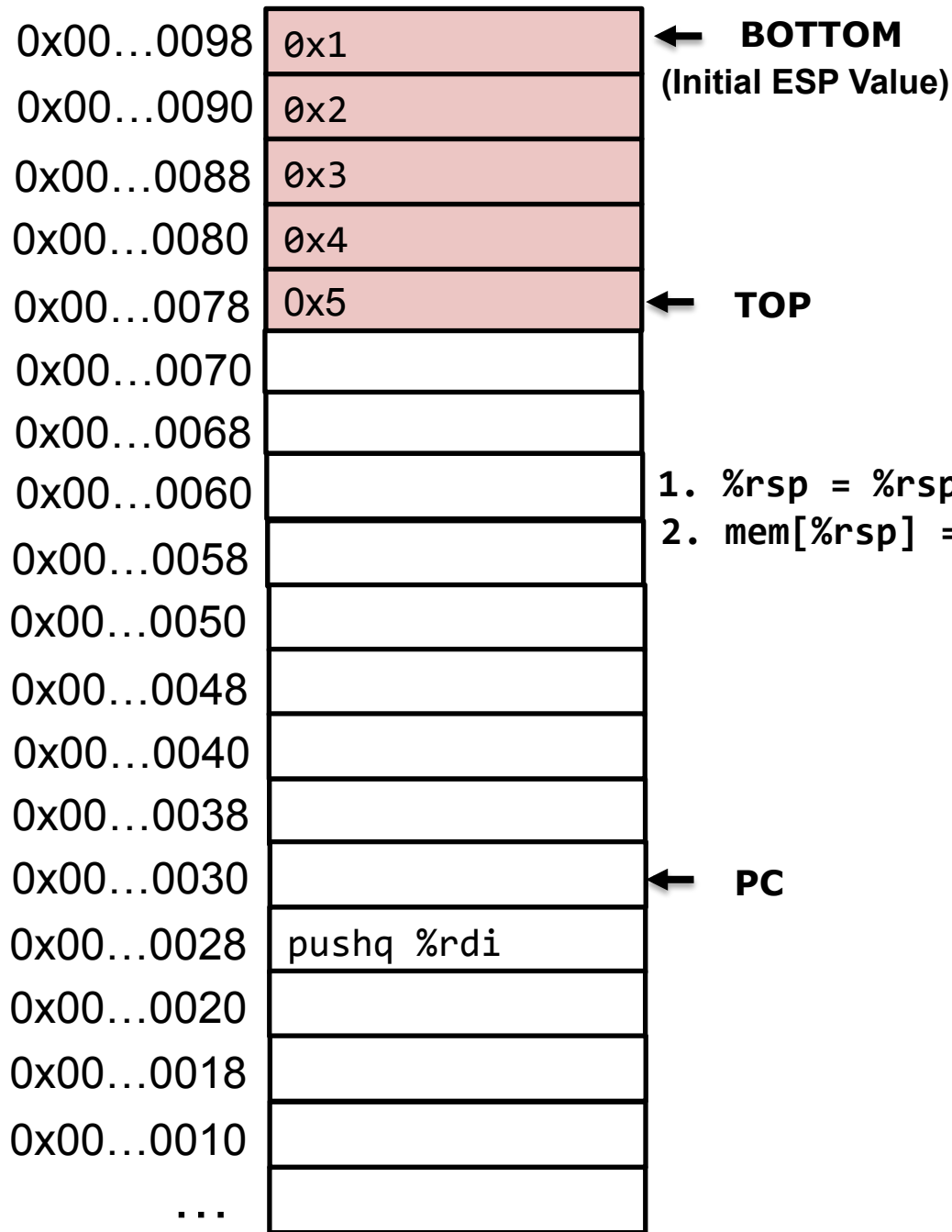
Memory





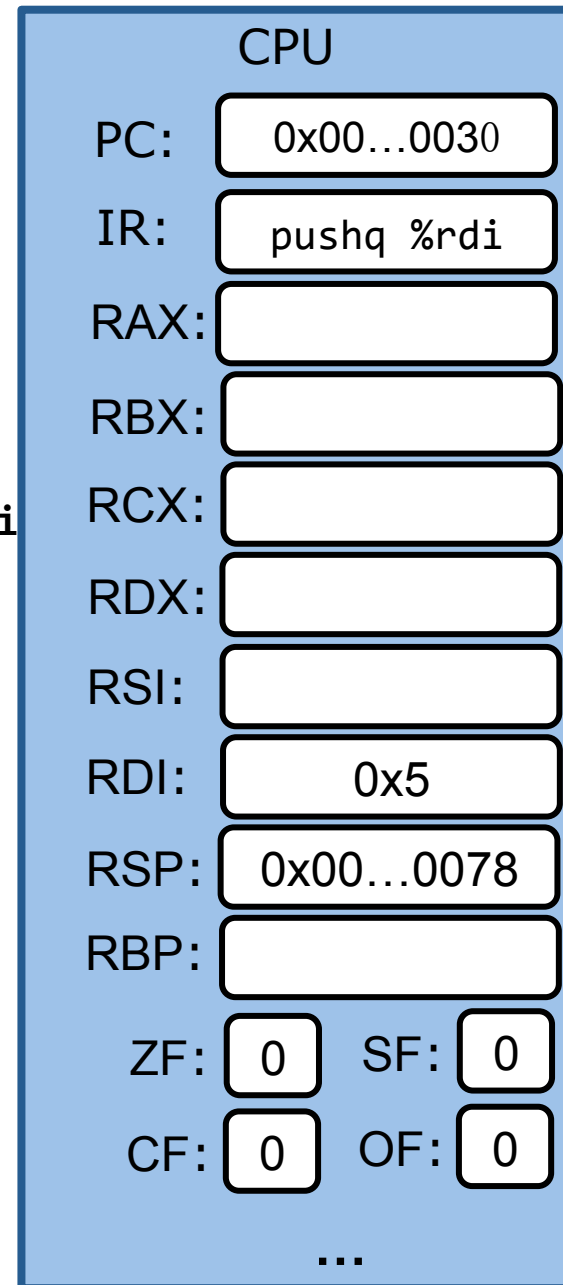
Memory





1. $\%rsp = \%rsp - 8$
2. $mem[\%rsp] = \%rdi$

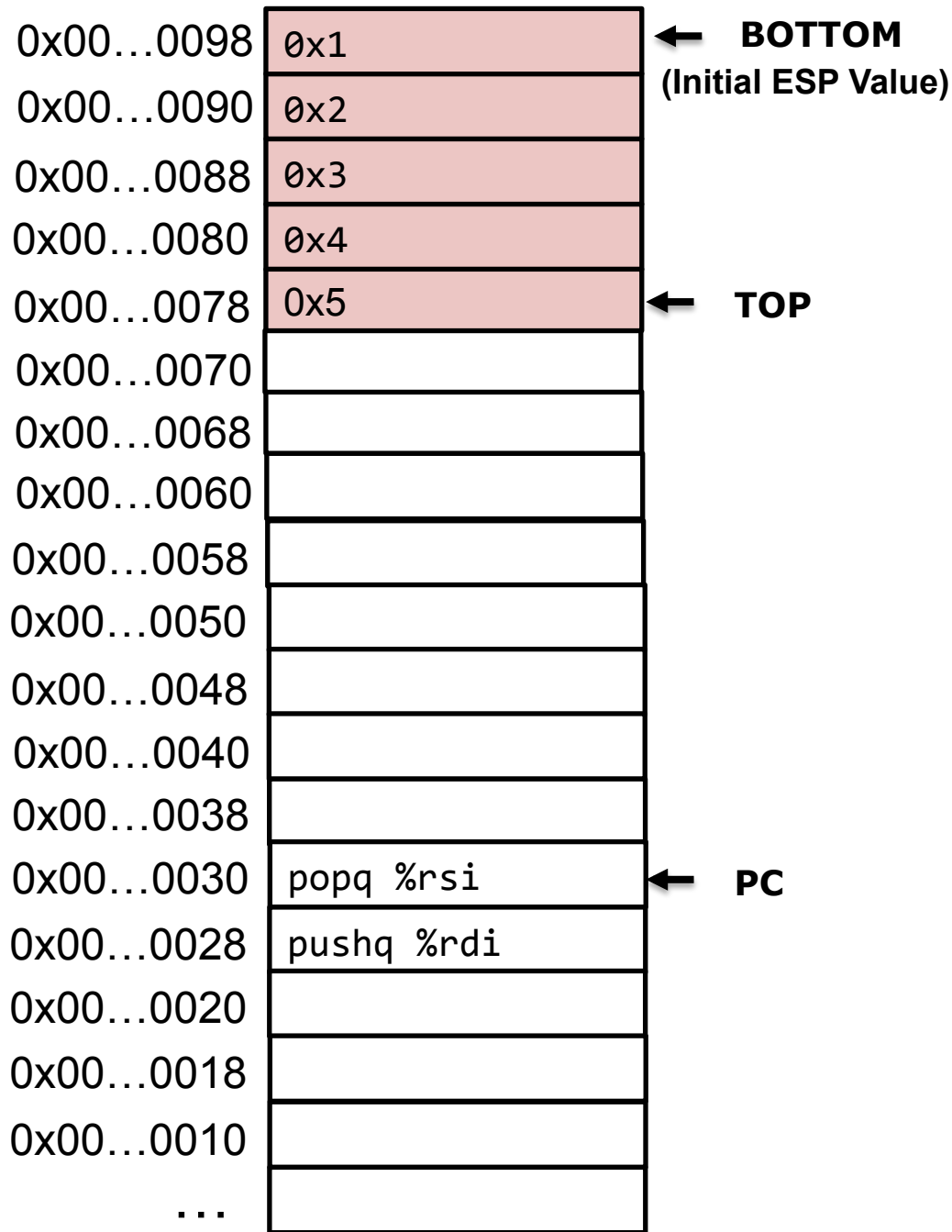
Memory



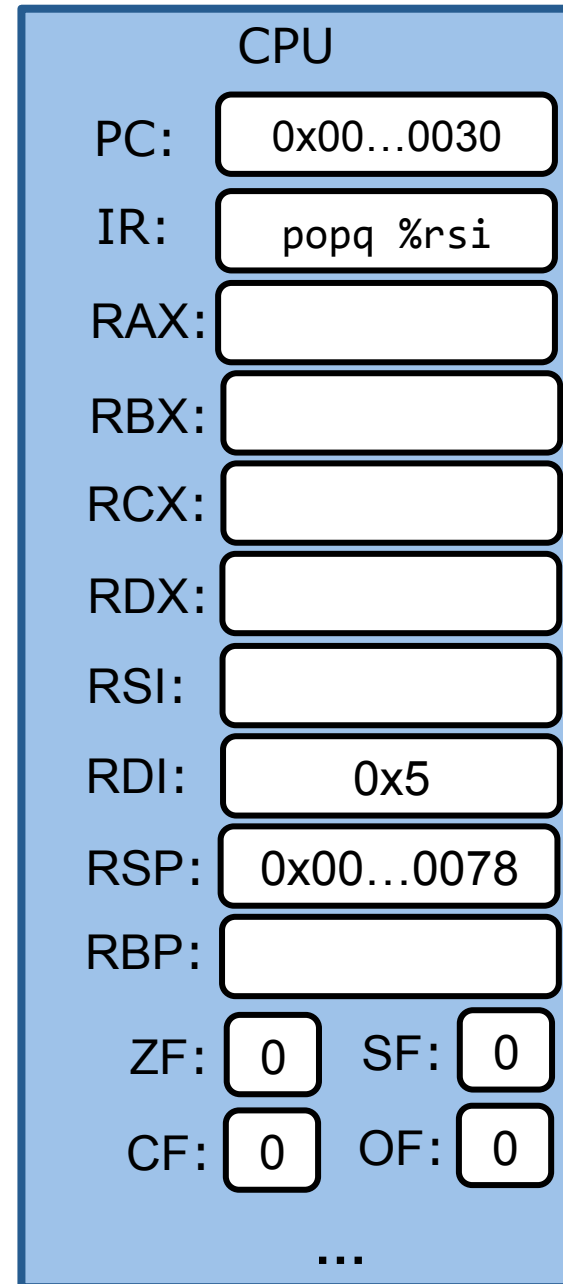
Stack – pop Instruction

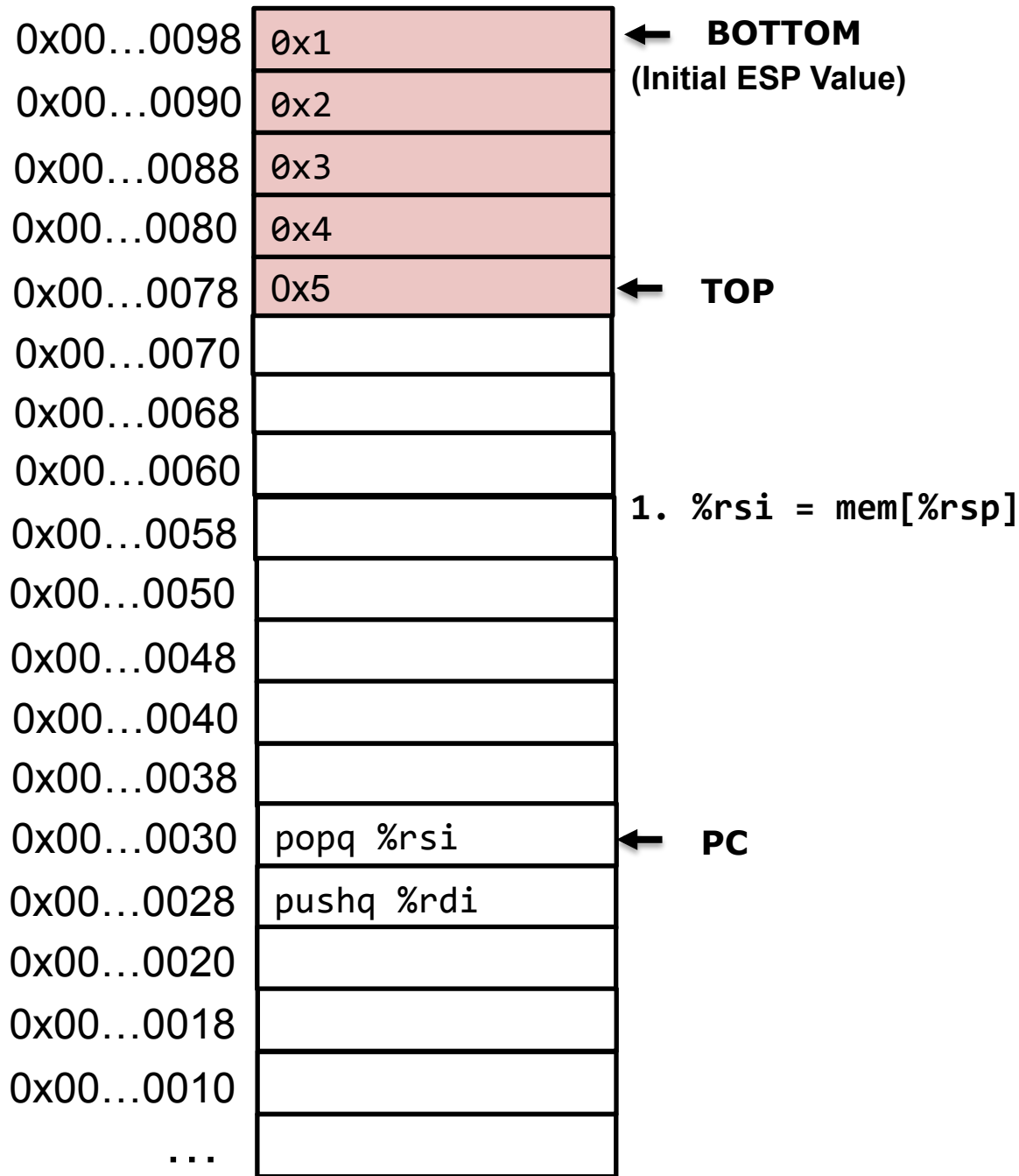
popq dest

- Store the value at address %rsp to dest
- Increment %rsp by 8

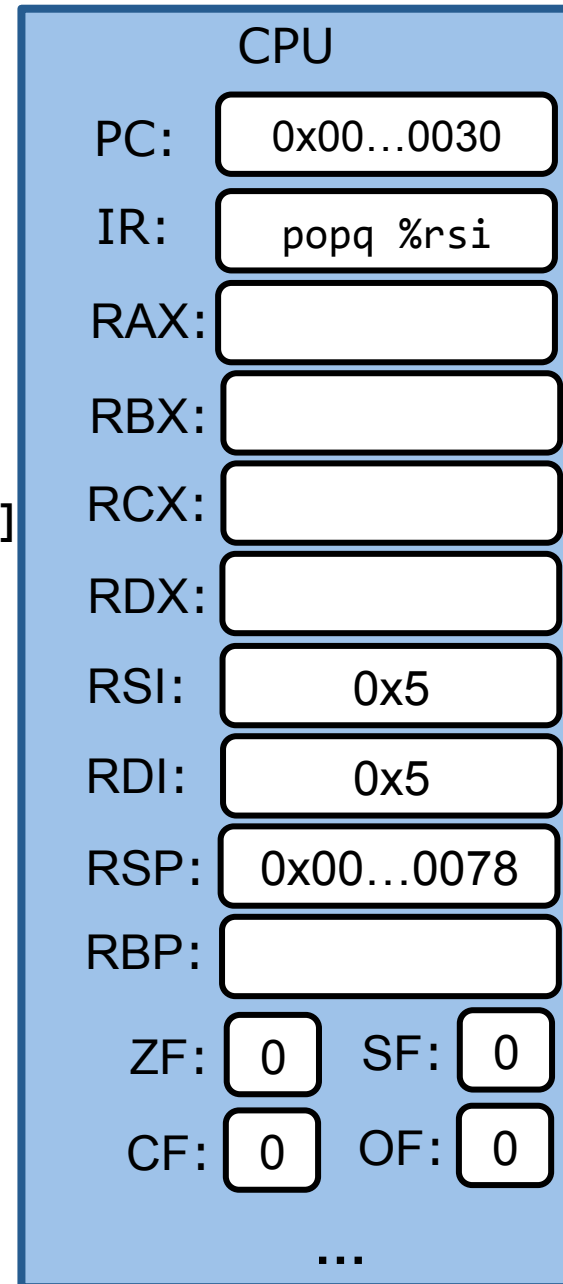


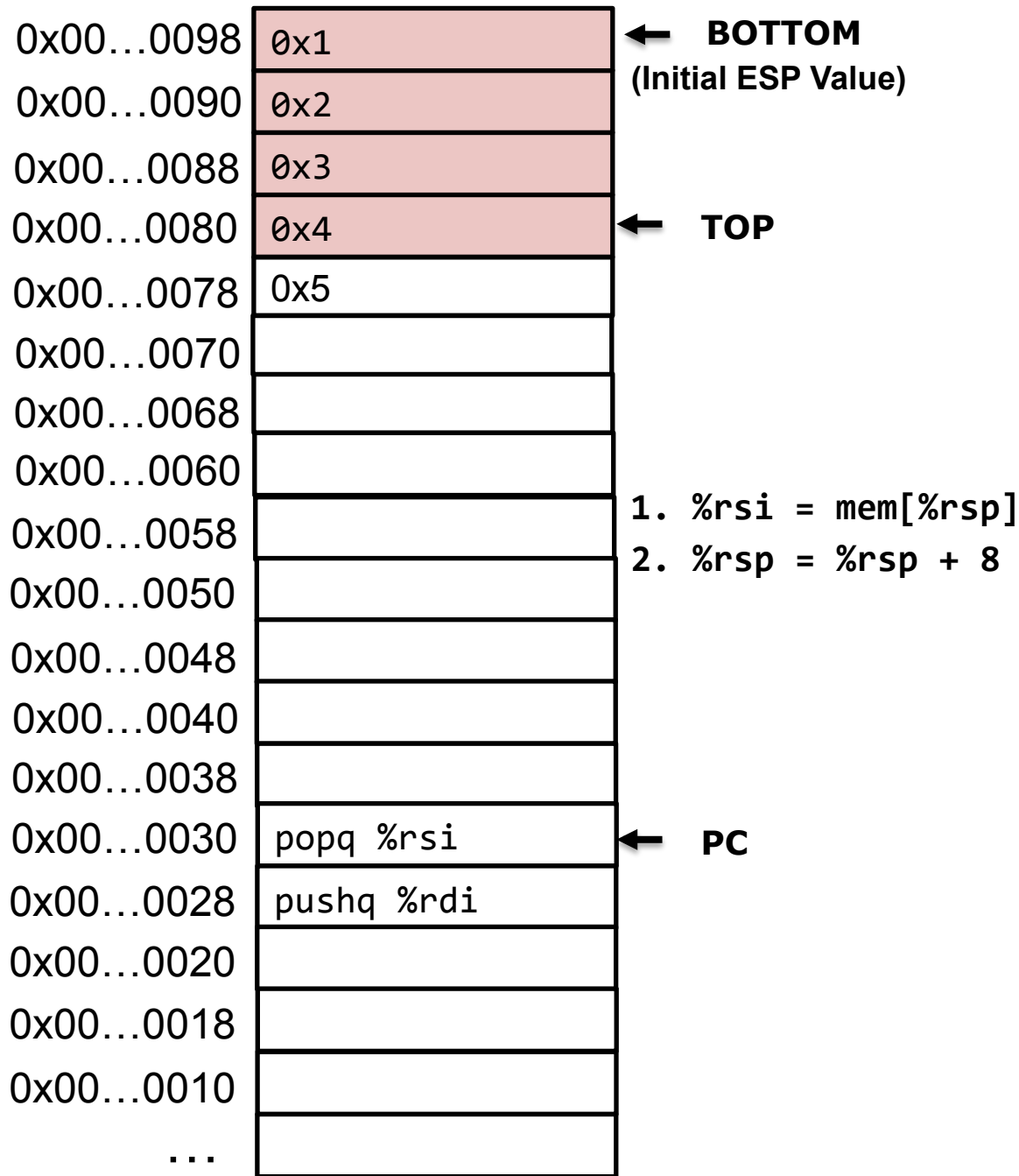
Memory



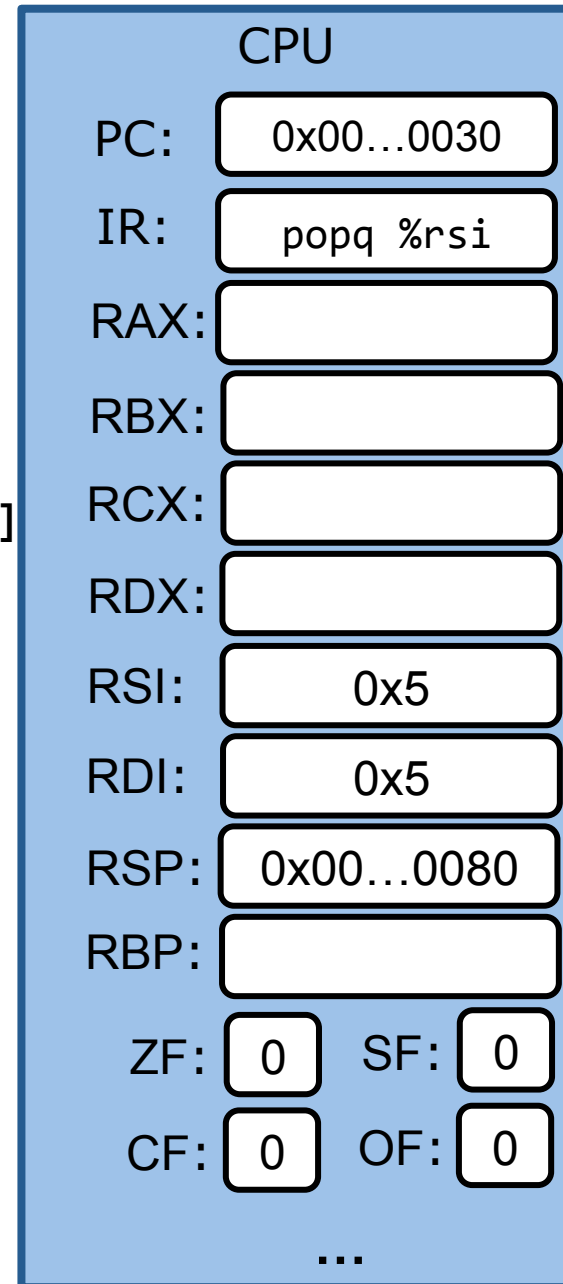


Memory





Memory



Control transfer from caller to callee

call label(func name)

- Push return address on stack
 - Current pc + 8
- Jump label
 - Change the pc to the address of the label

```
int add(int a, int b) {  
    int c = a + b;  
    return c;  
}  
  
int main() {  
    int a = 0;  
    int b = 2;  
    int c = add(a, b);  
    printf("%d\b", c);  
    return 0;  
}
```

Control transfer – call Instruction

call label(func name)

- Push the return address on stack
 - Return address points to the next instruction after **call**
- Jump label
 - Change the pc to label's value

```
add:                                main:
    leal (%rdi,%rsi), %eax          movl   $2, %esi
    ret                             movl   $0, %edi
                                    call   add
                                    movl   %eax, %edx
                                    ...
```

*GCC -Og *.c*

return address points to this instruction

Control transfer from callee back to caller

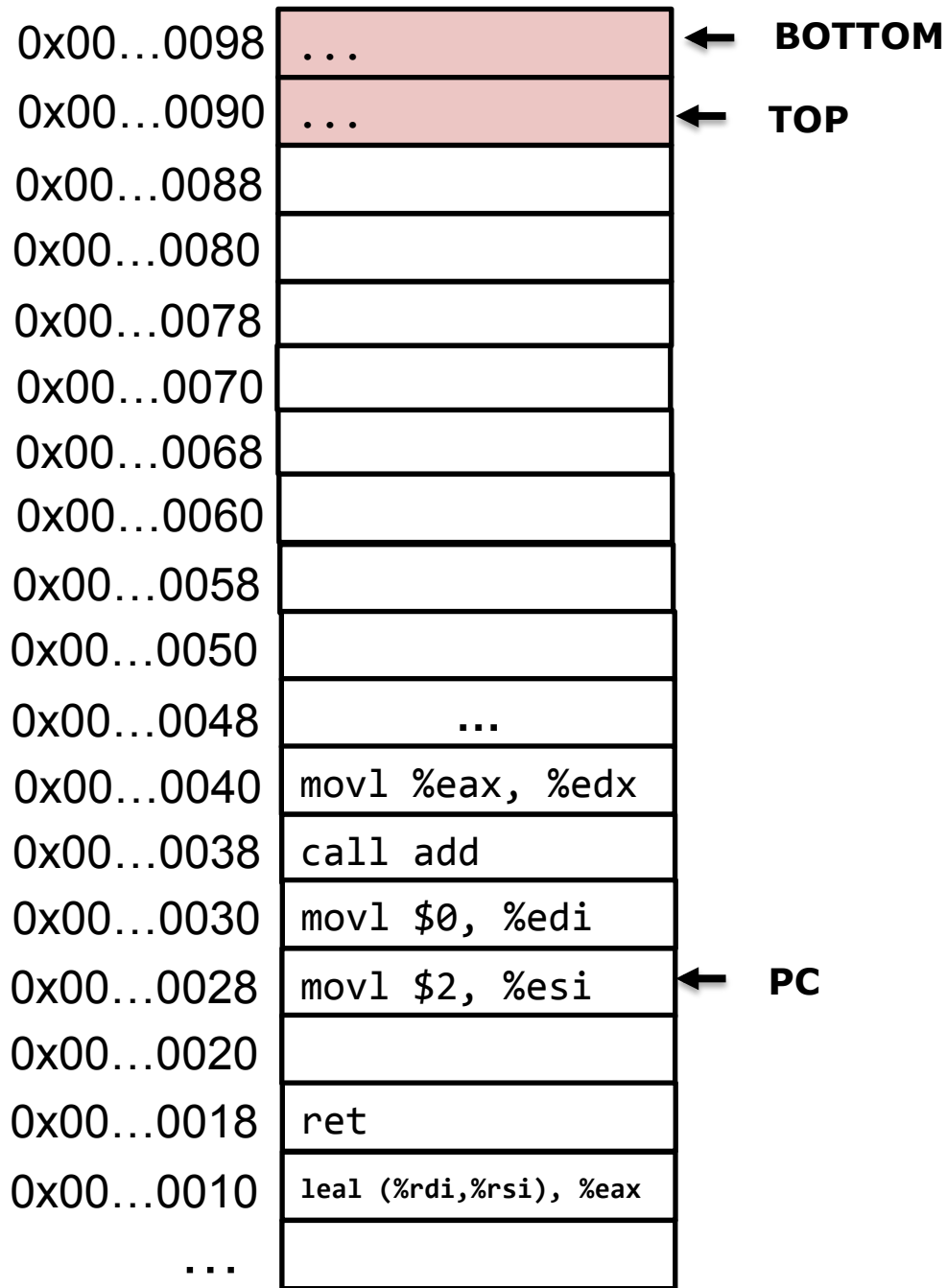
ret

- Pop 8 bytes from the stack to PC
 - `pc = mem[%rsp]`

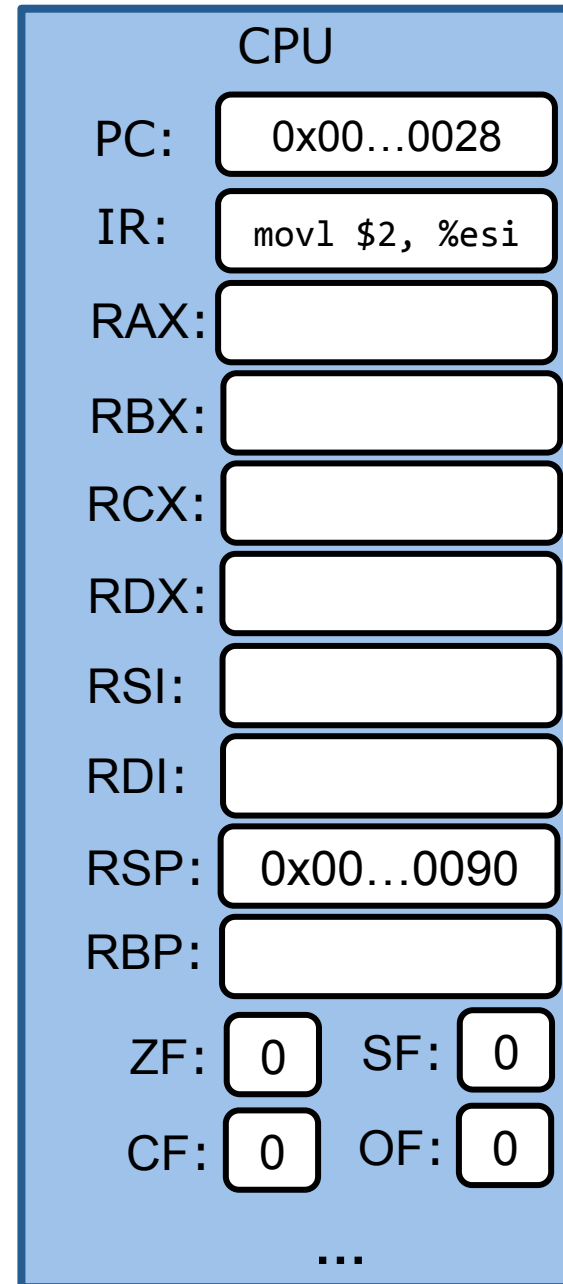
```
add:
    leal (%rdi,%rsi), %eax
    ret
```

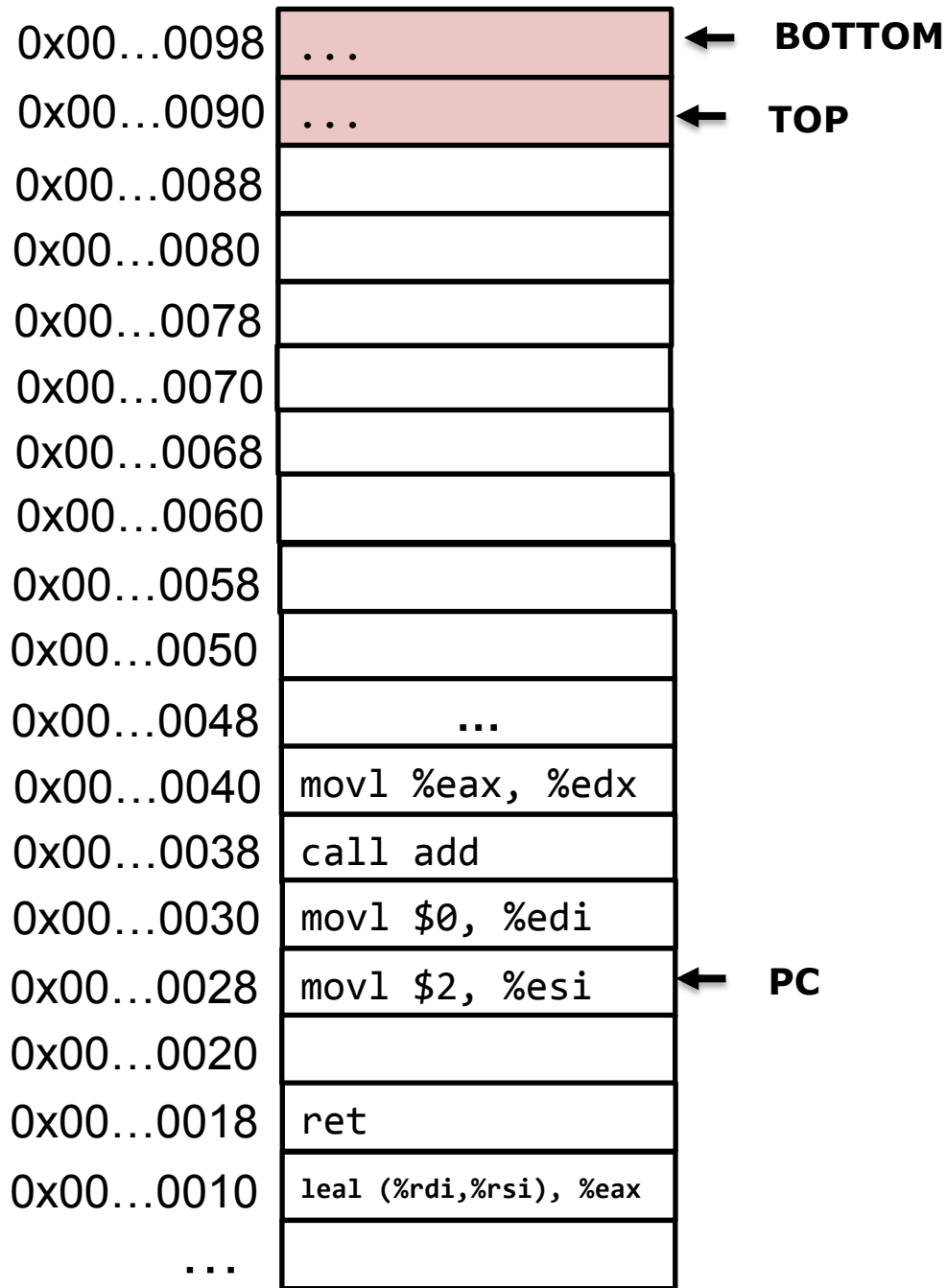
```
main:
    movl $2, %esi
    movl $0, %edi
    call add
    movl %eax, %edx
    ...
```

GCC -Og *.c

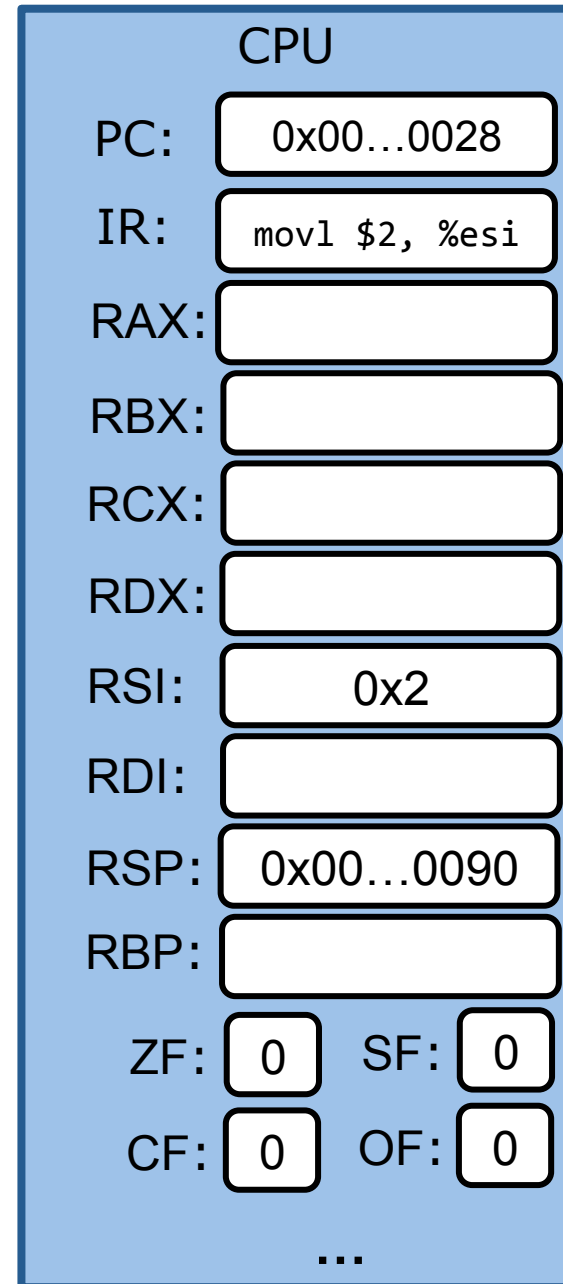


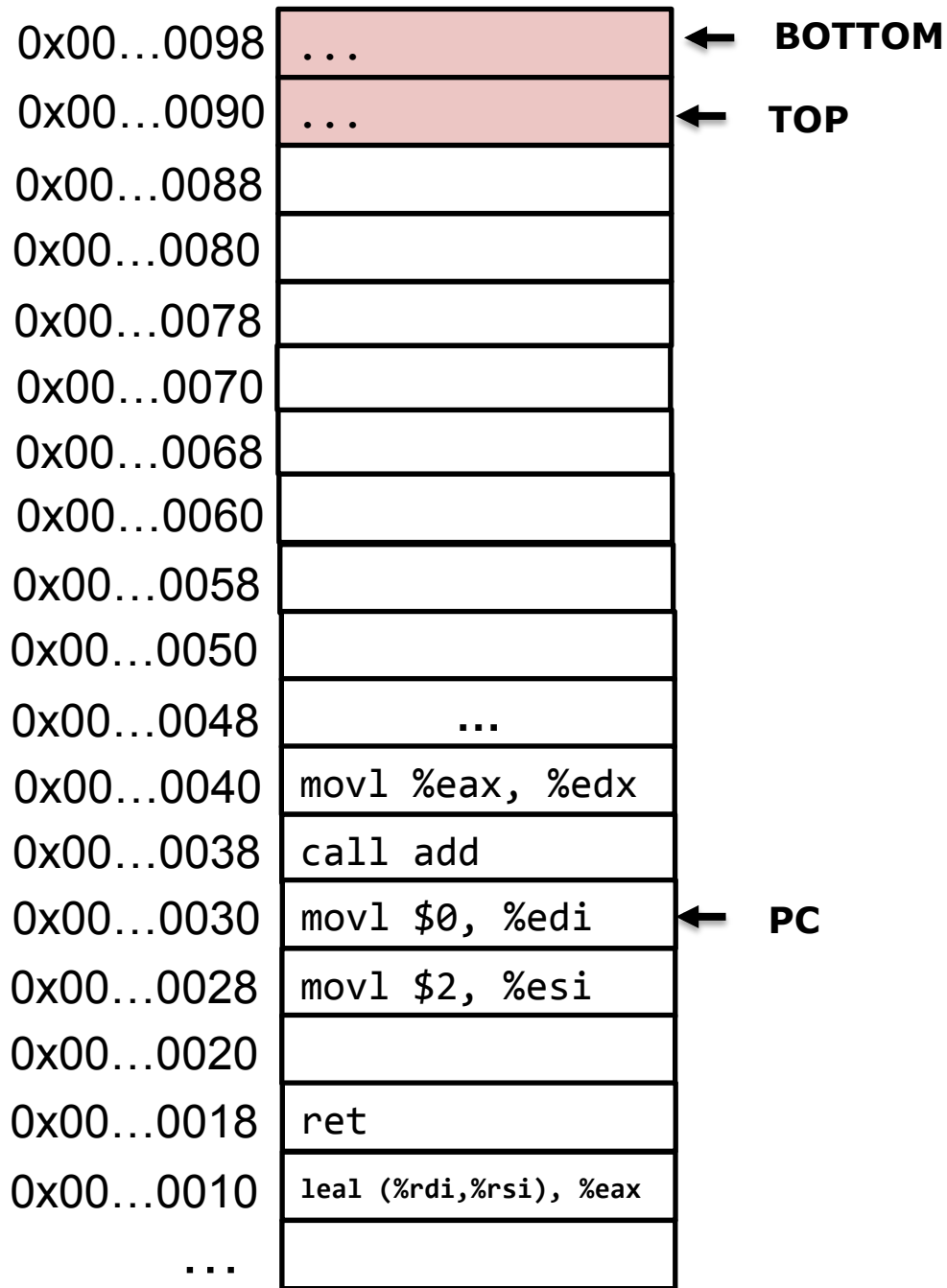
Memory



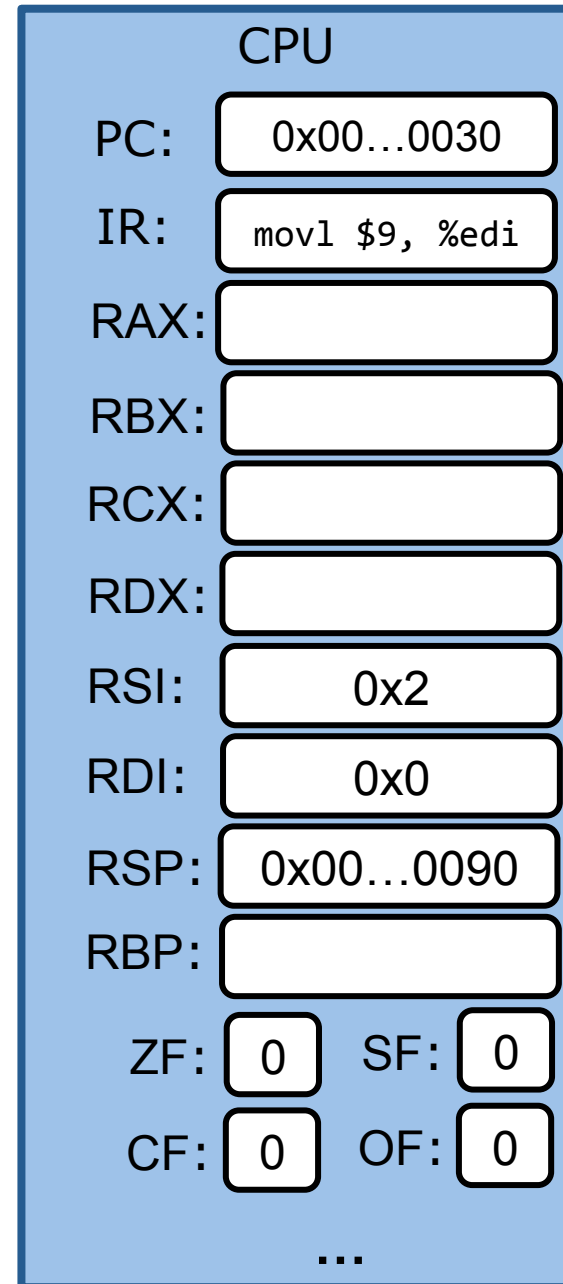


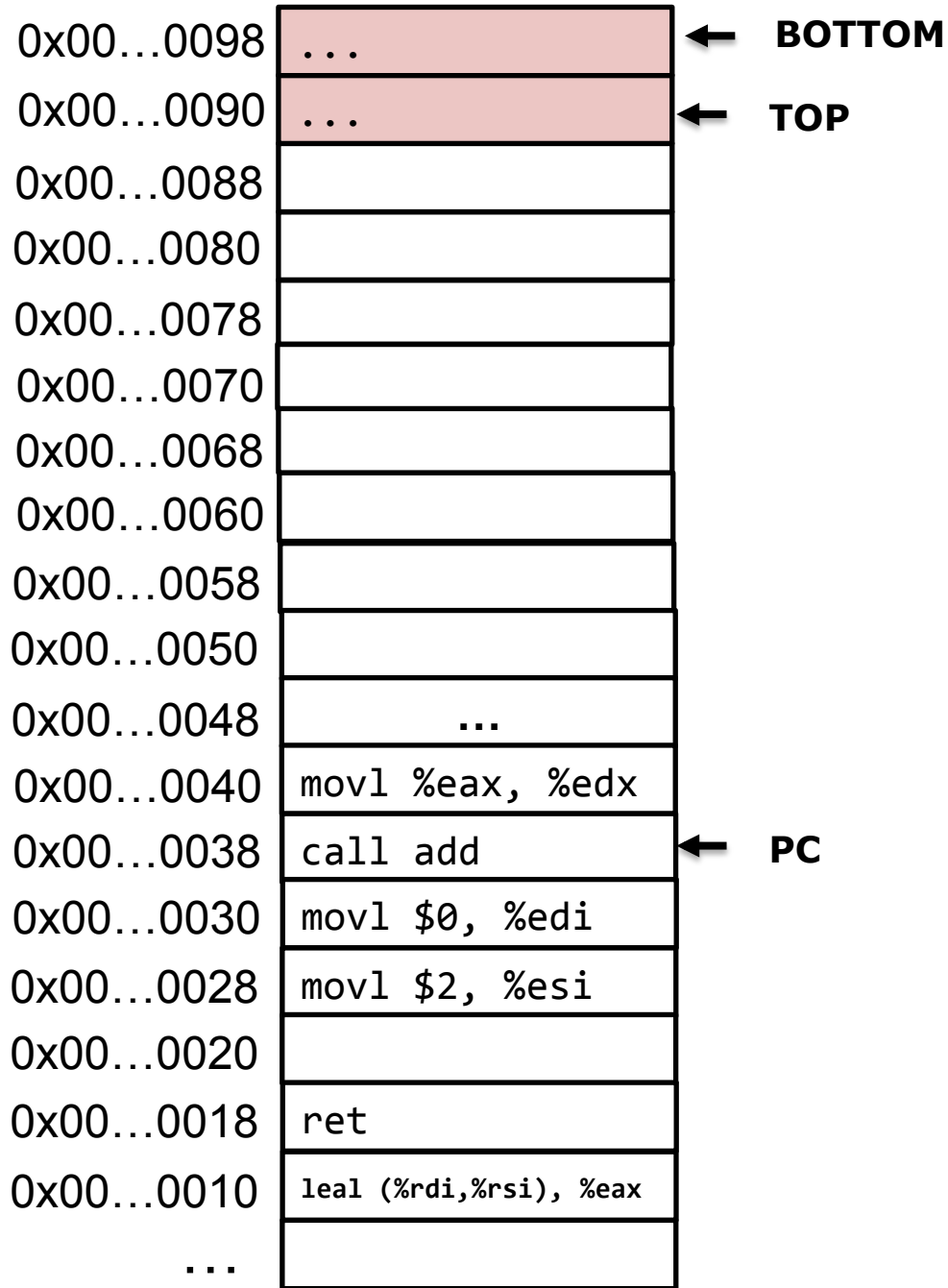
Memory



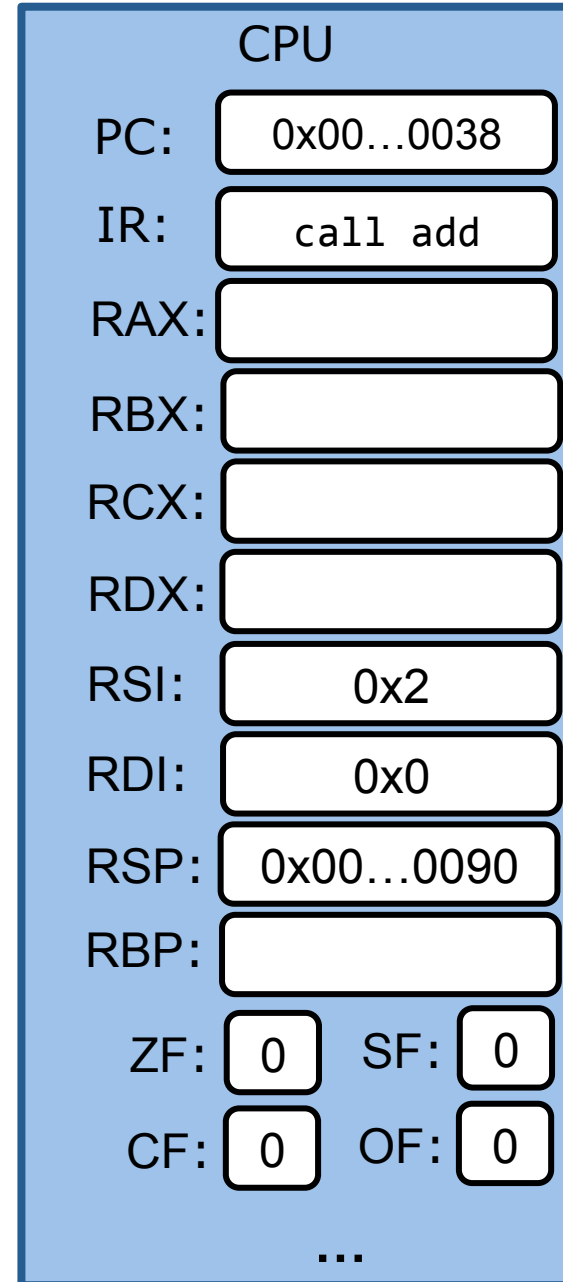


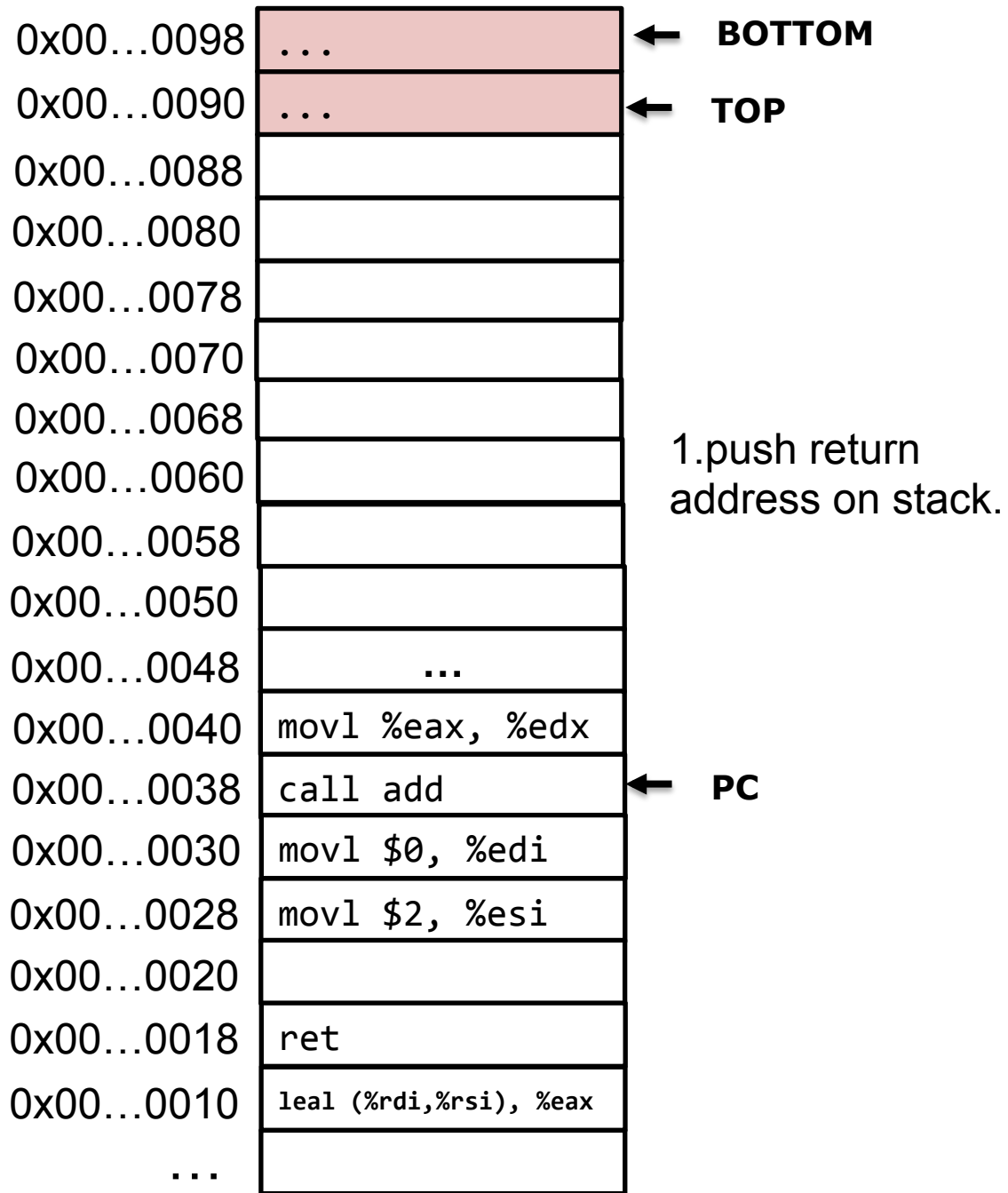
Memory



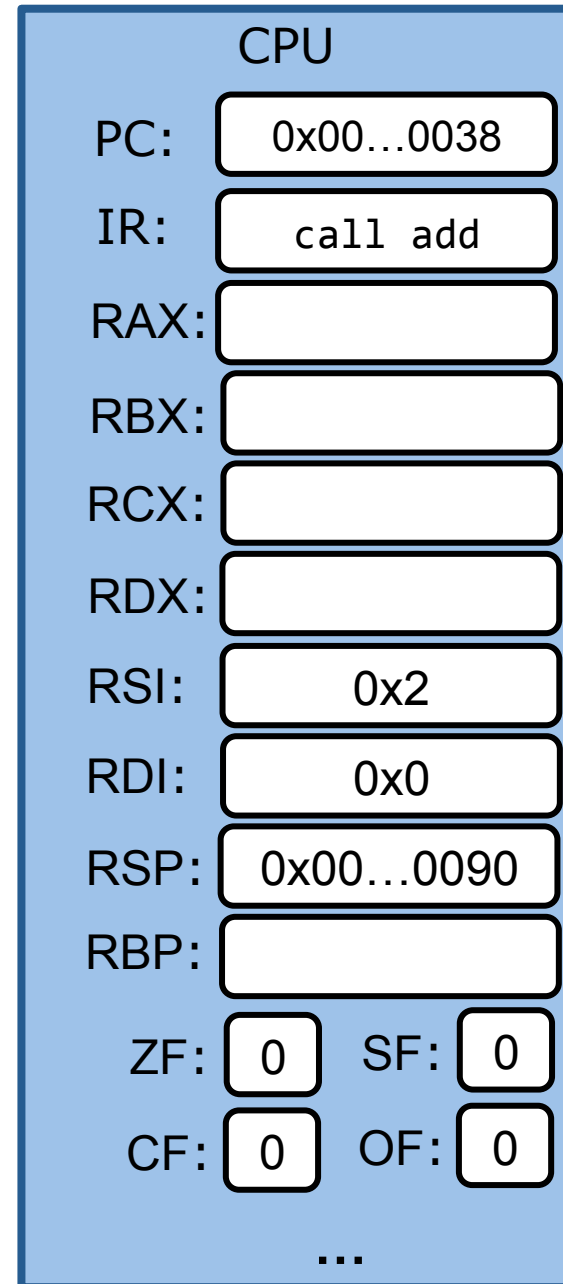


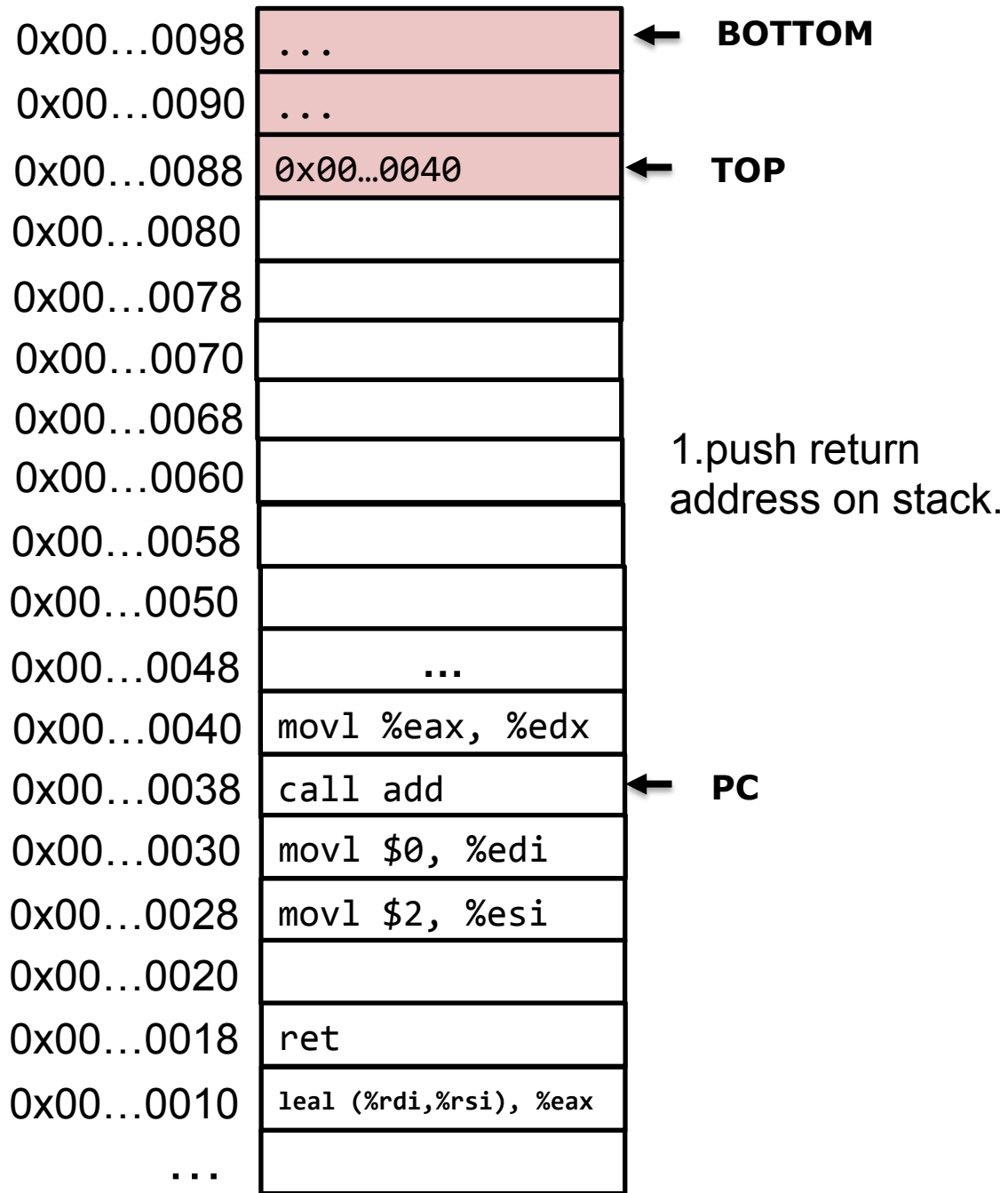
Memory



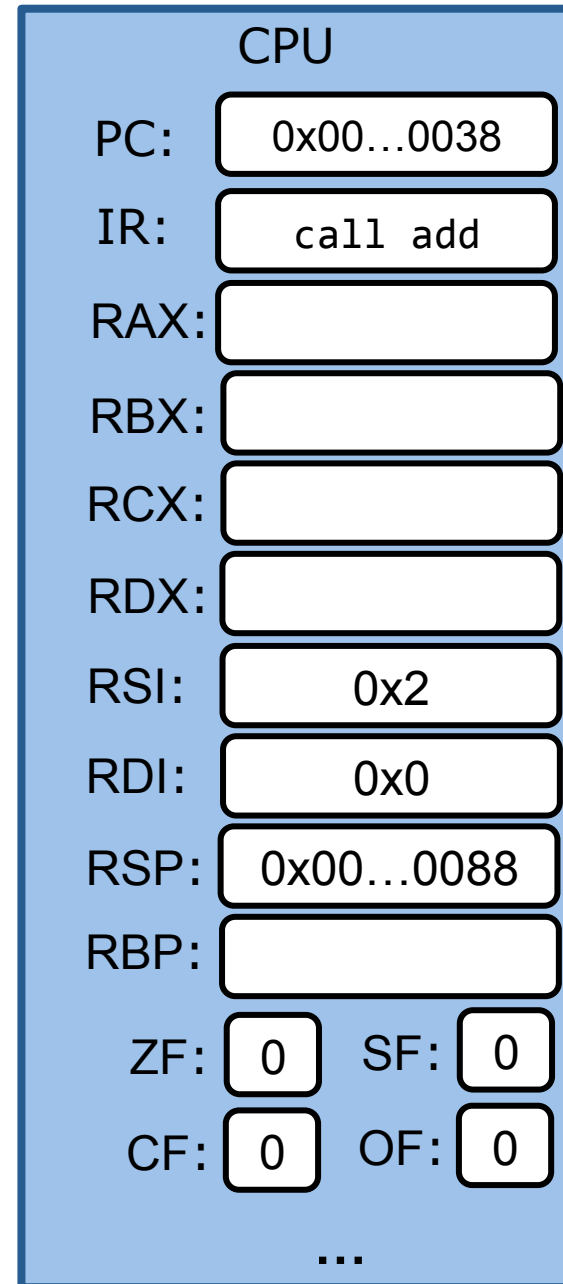


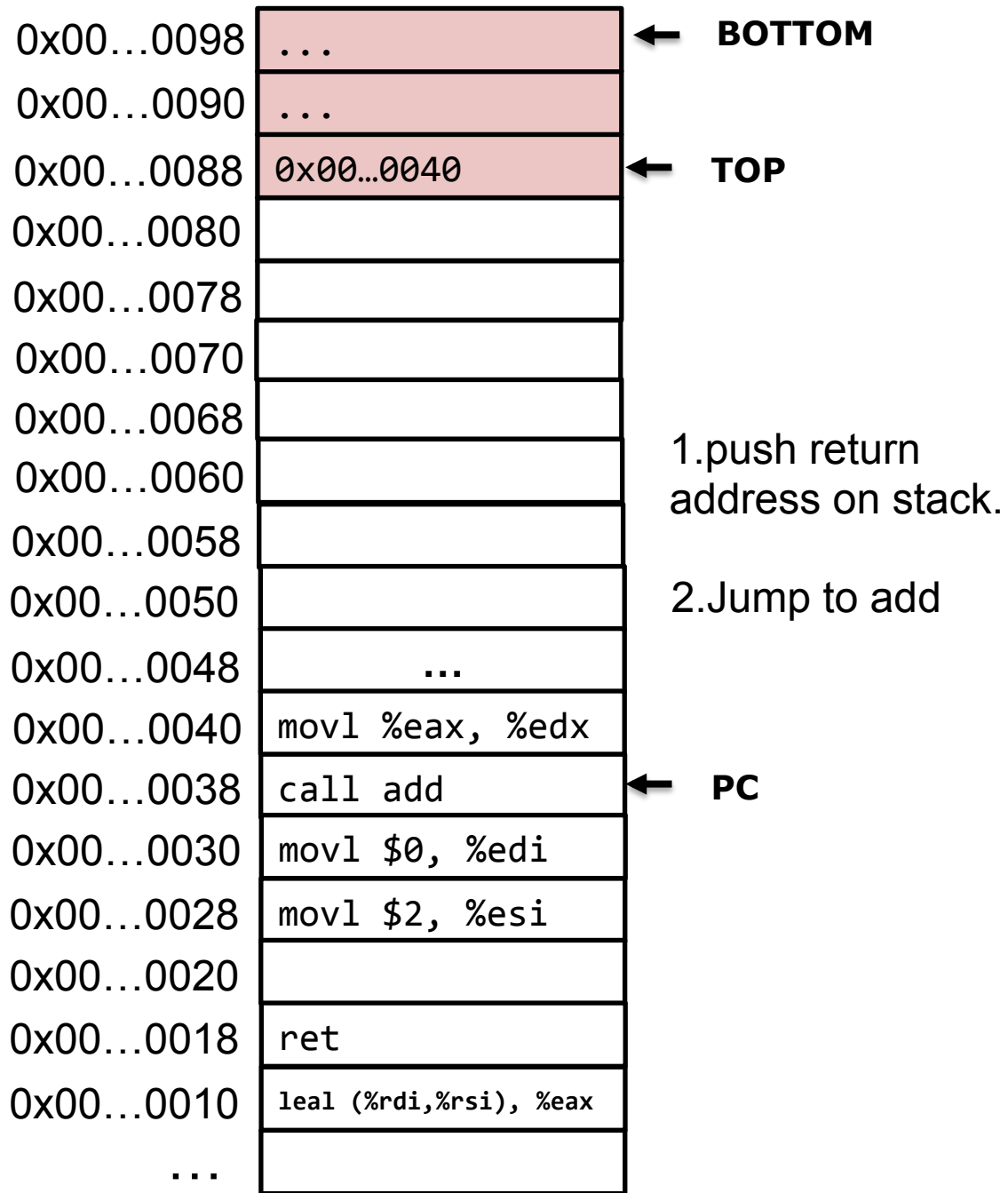
Memory





Memory

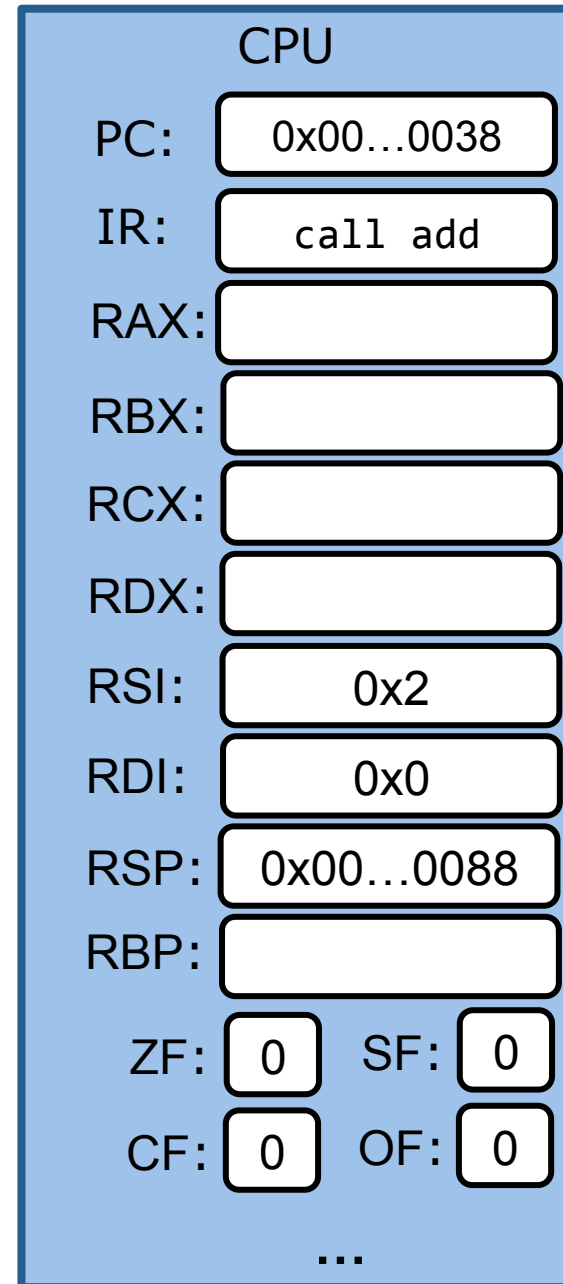


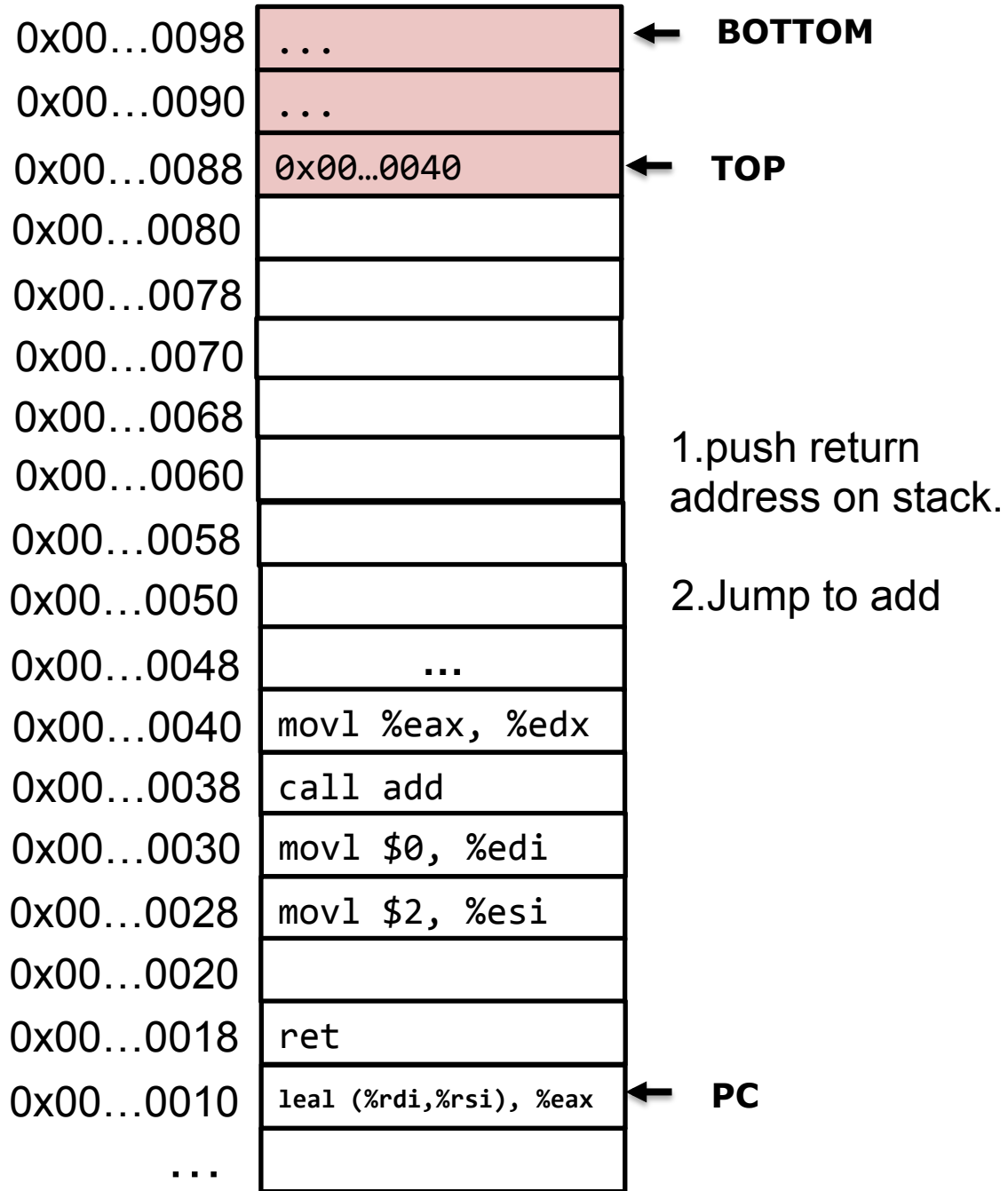


Memory

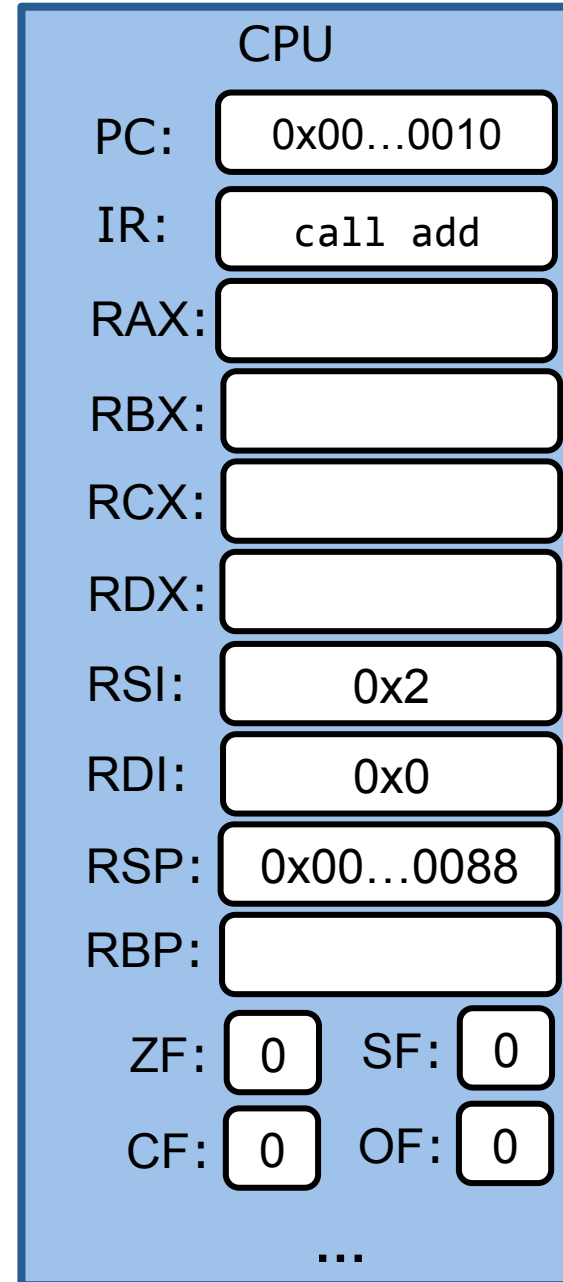
1. push return address on stack.

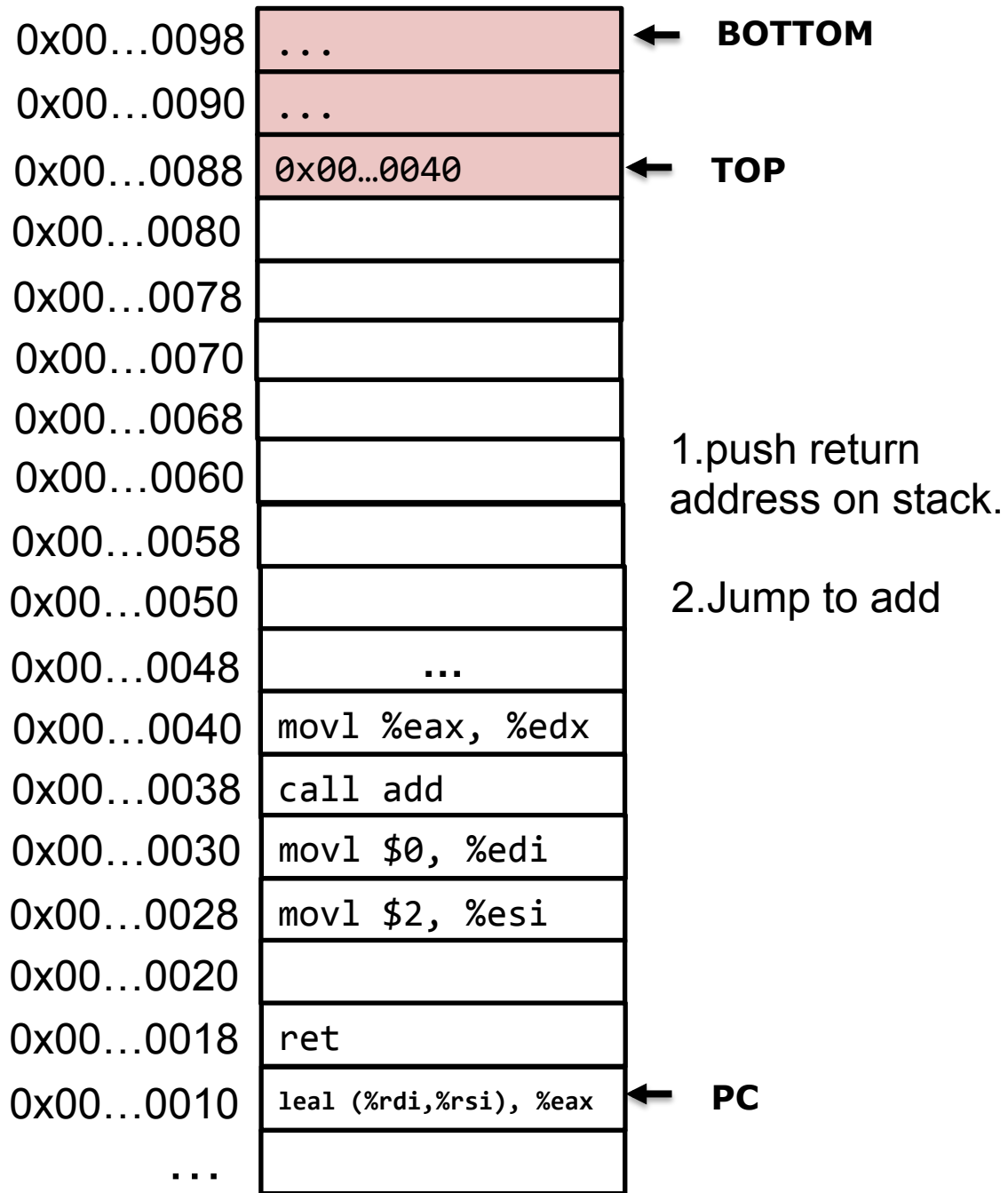
2. Jump to add



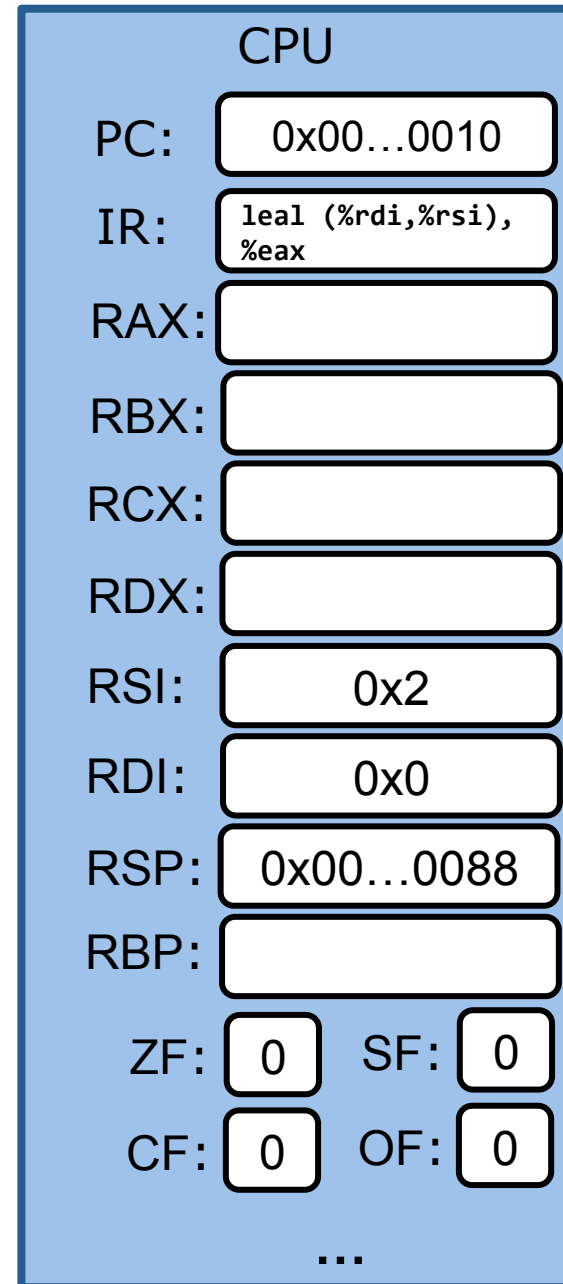


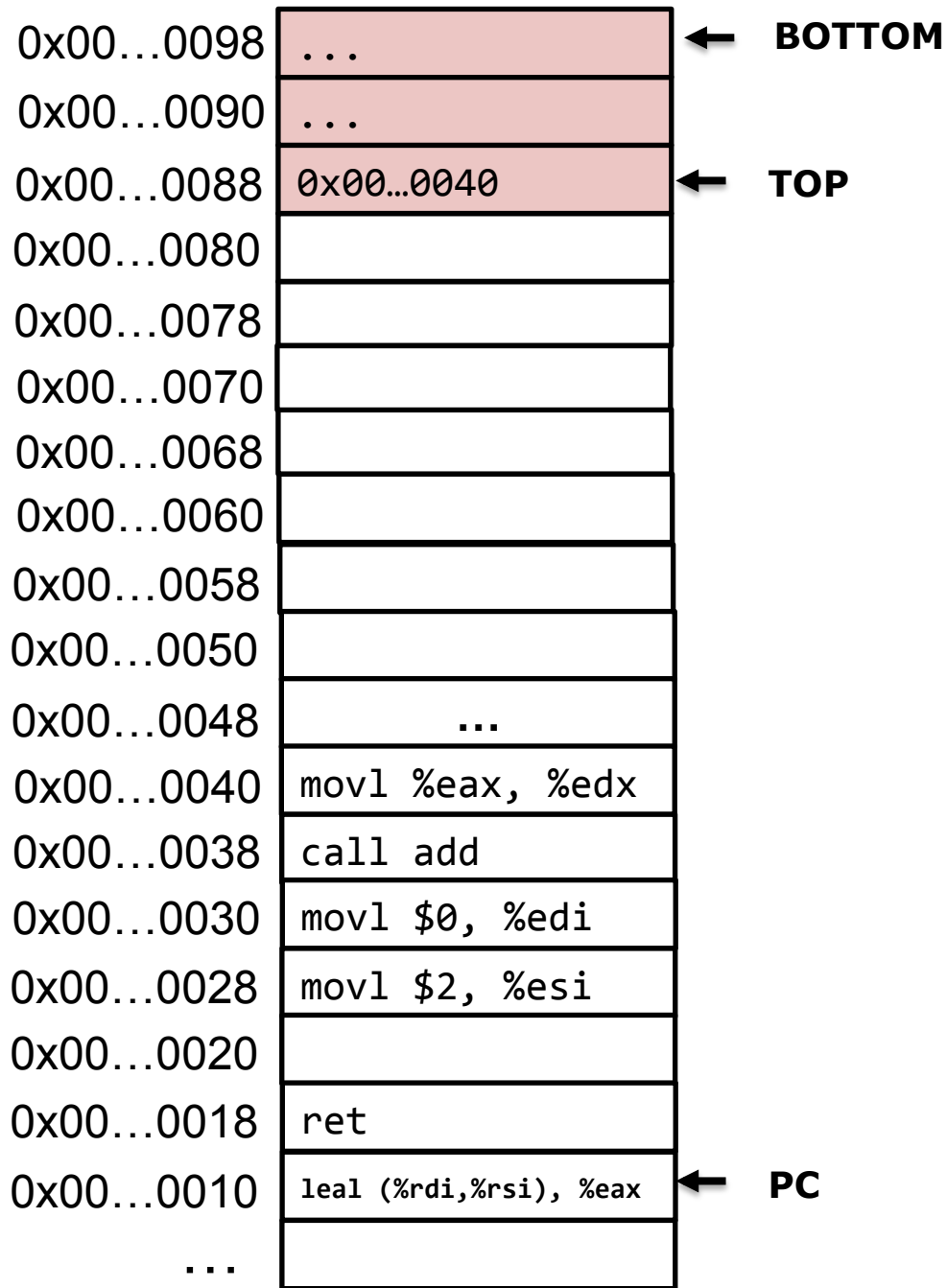
Memory



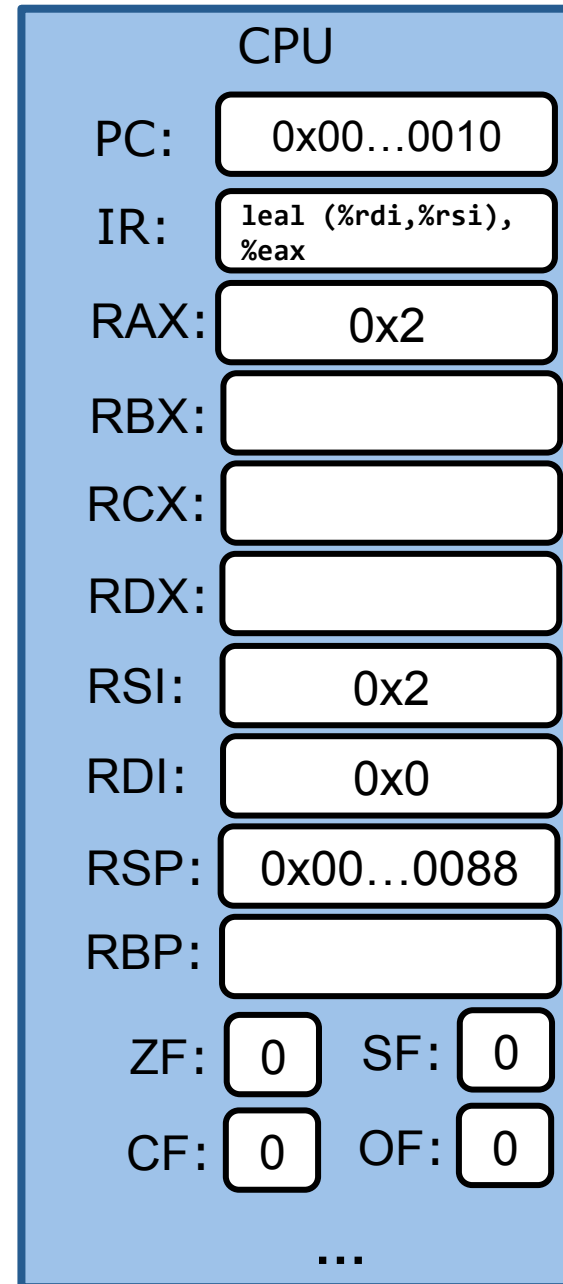


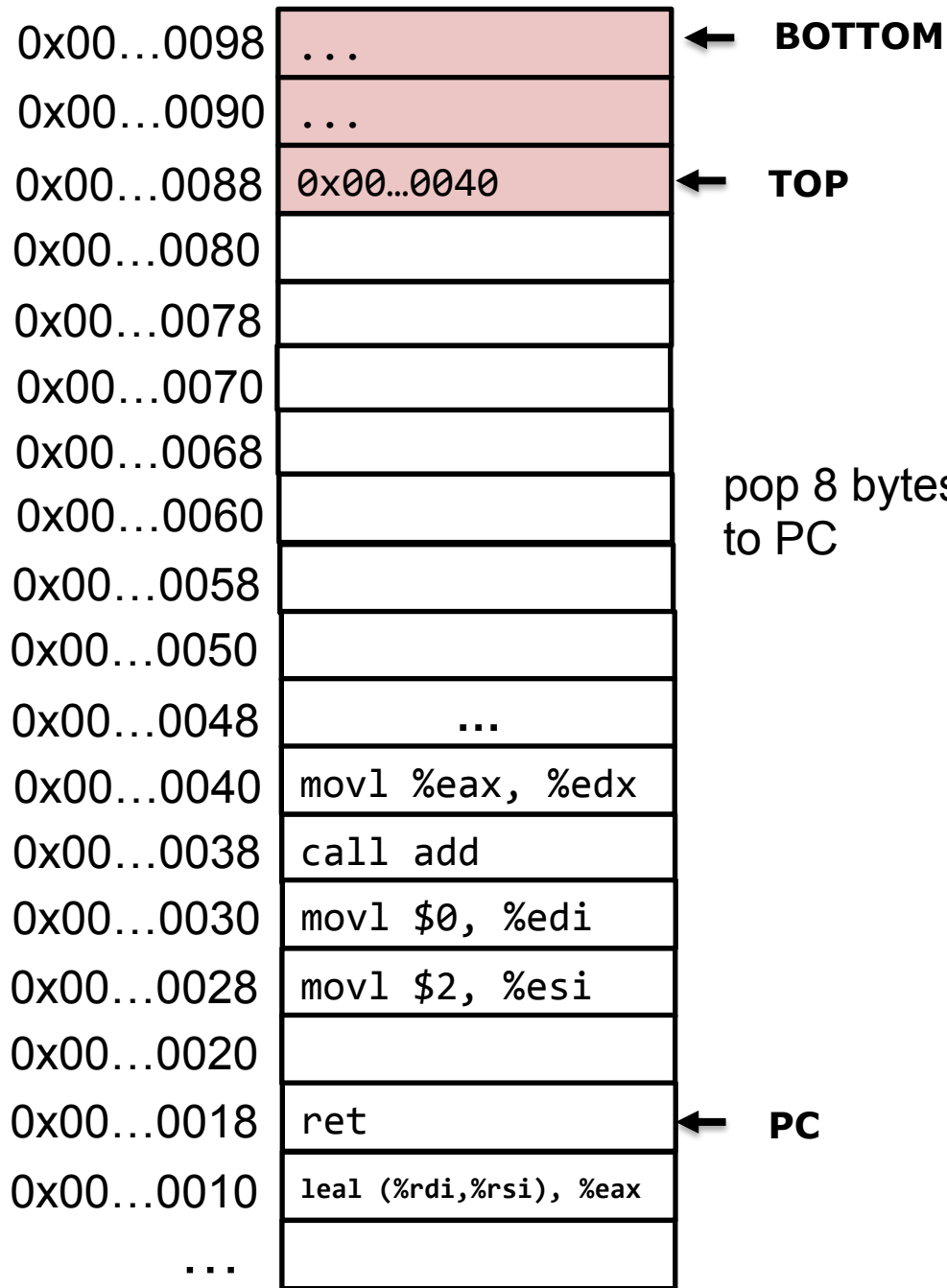
Memory





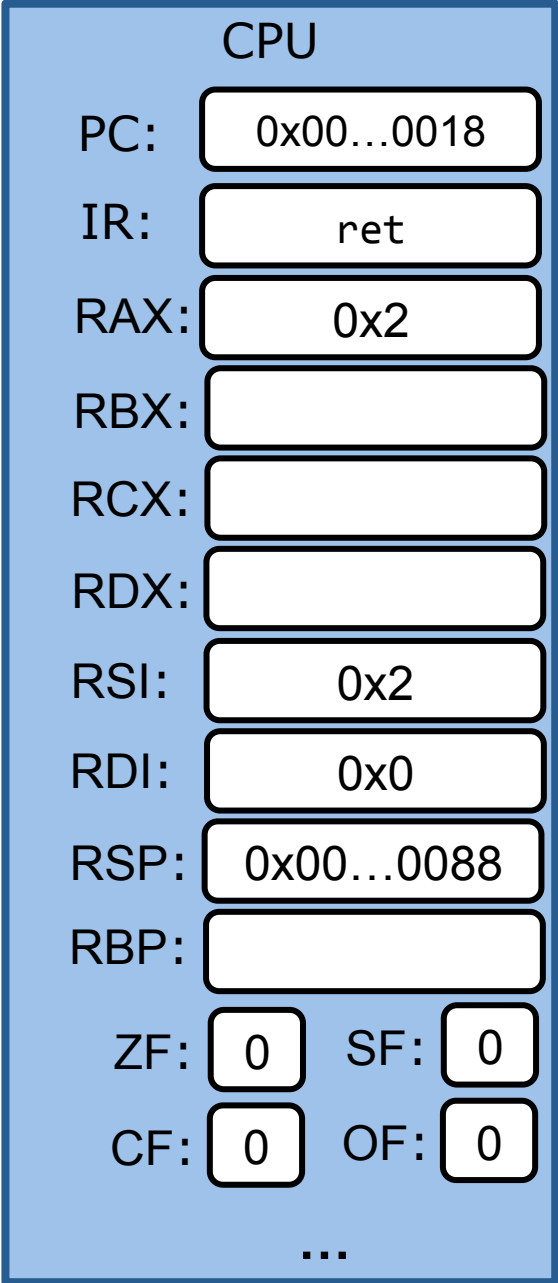
Memory

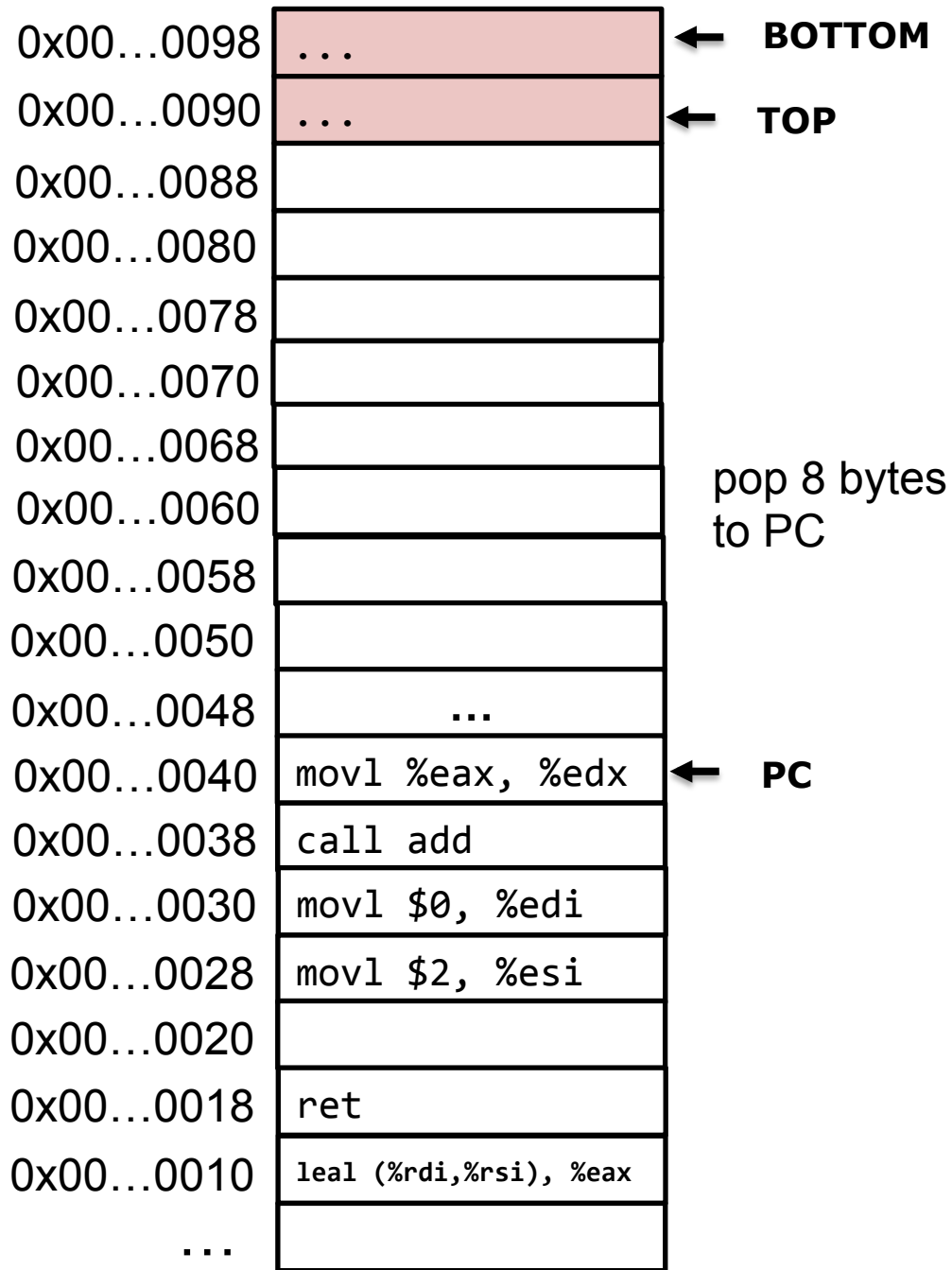




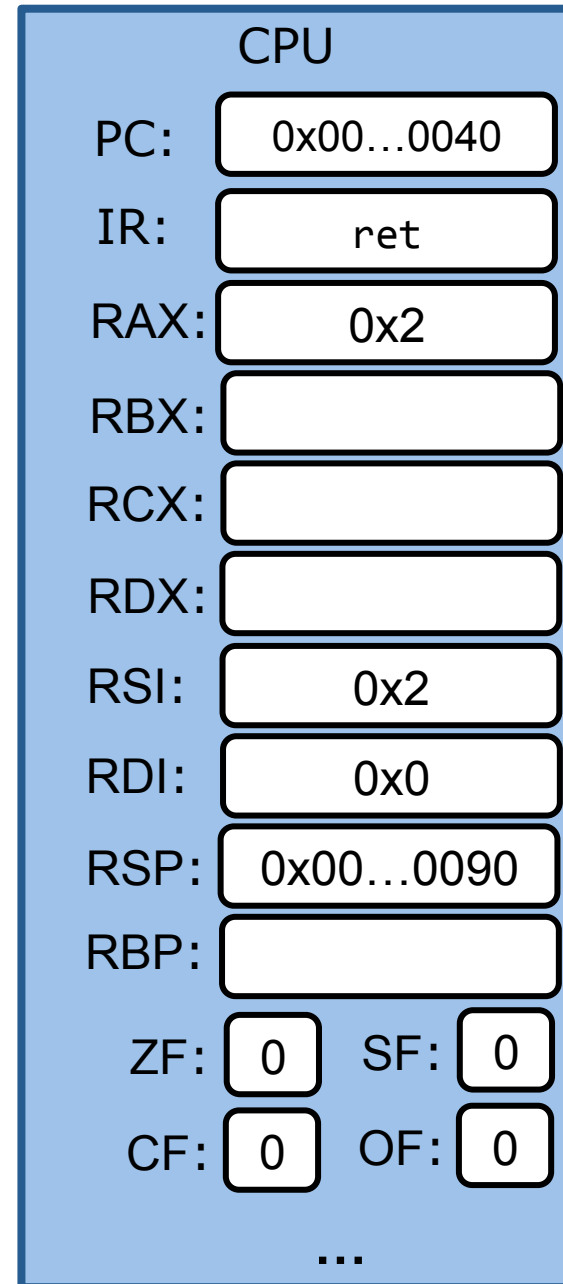
pop 8 bytes
to PC

Memory






Memory



Where to store function arguments and return values?

- Hardware does not dictate where arguments and return value are stored
 - It's up to the software (compilers).
- Where to put arguments/return value?
 - Arguments and return value are like local variables
 - They are allocated when function is called, de-allocated when function returns.
 - Must do such allocation/de-allocation very fast

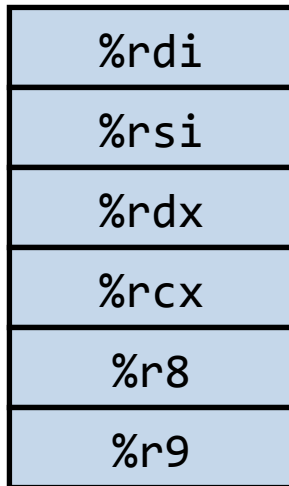
Where to store function arguments and return values?

- Two possible designs:
 - Store everything on stack
 - Use registers  Registers are much faster than memory but there are only a few of them
- The chosen design → the calling convention
 - All code on a computer system must obey the same convention
 - Otherwise, libraries won't work

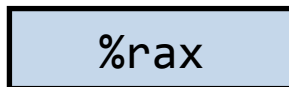
C/UNIX's calling convention

Registers

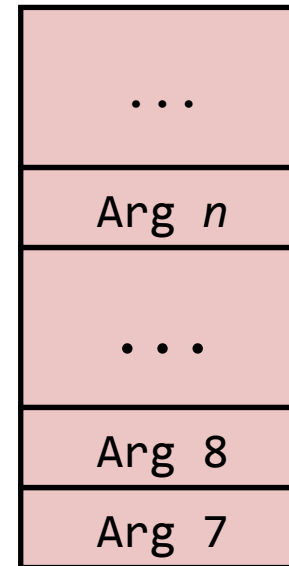
First 6 arguments



Return value



Stack



Only allocate stack space when needed

C's calling convention: args/return values

Registers

- First 6 Arguments: %rdi, %rsi, %rdx, %rcx, %r8, %r9
- Return value: %rax

```
int add(int a, int b, int c, int d, int e, int f, int g, int h) {  
    int r = a + b + c + d + e + f + g + h;  
    return r;  
}
```

```
int main() {  
  
    int c = add(1, 2, 3, 4, 5, 6, 7, 8);  
    printf("%d\n", c);  
    return 0;  
}
```

C's calling convention: args/return values

```
int add(int a, int b, int c, int d, int e, int f, int g, int h) {  
    int r = a + b + c + d + e + f + g + h;  
    return r;  
}
```

main:

```
pushq    $8  
pushq    $7  
movl     $6, %r9d  
movl     $5, %r8d  
movl     $4, %ecx  
movl     $3, %edx  
movl     $2, %esi  
movl     $1, %edi  
call     add
```

add:

```
addl     %esi, %edi  
addl     %edi, %edx  
addl     %edx, %ecx  
addl     %r8d, %ecx  
addl     %r9d, %ecx  
movl     %ecx, %eax  
addl     8(%rsp), %eax  
addl     16(%rsp), %eax  
ret
```

8(%rsp) stores g

16(%rsp) stores h
what does (%rsp) store?

How to allocate/deallocate local variables?

Use registers whenever possible

Allocate local variables on the stack

- `subq $0x8,%rsp //allocate 8 bytes`
- `movq $1, 8(%rsp) //store 1 in the allocated 8 bytes`

Calling convention: Caller vs. callee-save registers

- What can the caller assume about the content of a register across function calls?

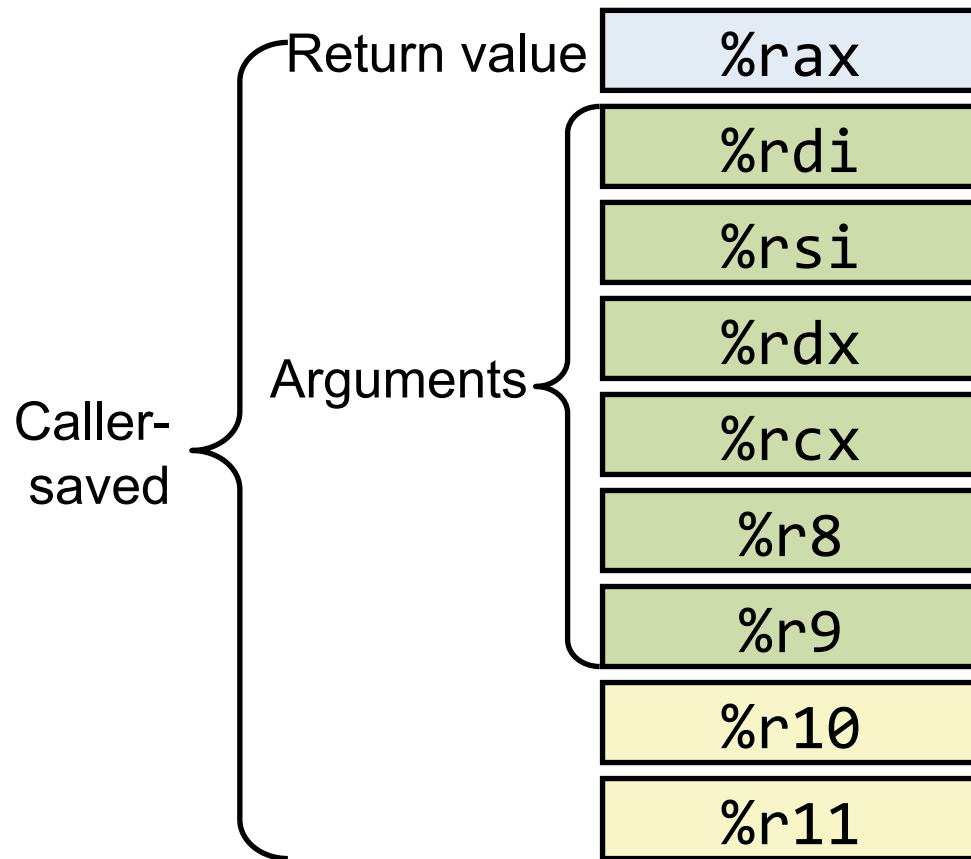
```
int foo() {  
    int a;    // suppose a is stored in %r12  
    a = .... // compute result of a  
  
    int r = bar();  
  
    int result = r + a; // does %r12 still store the value of a?  
    return result;  
}
```

Calling convention: register saving

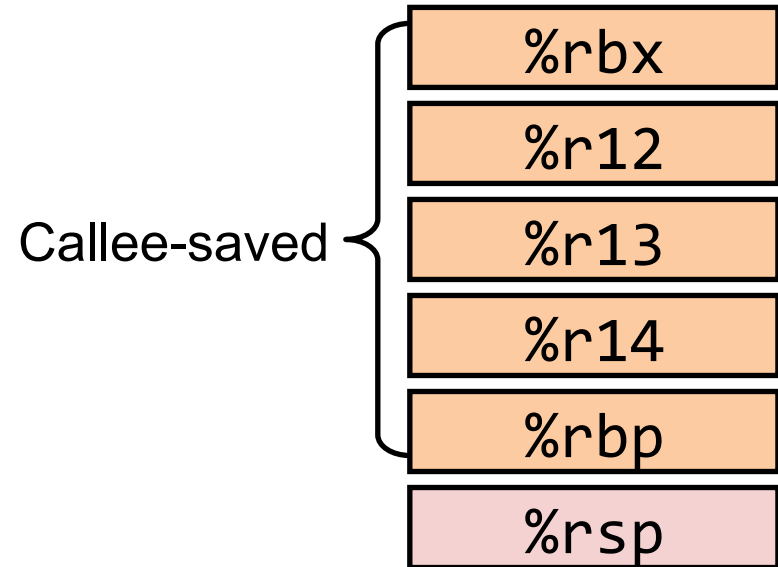
Some registers are “caller saved”, others are “callee saved”

- Caller saved
 - Caller saves “caller saved” registers on stack before the call
- Callee saved
 - Callee saves “callee saved” registers on stack before using
 - Callee restores them before returning to caller

C' calling convention: Register Usage



Callee can directly use these registers



Caller can assume these registers are unchanged.

Example

```
int add2(int a, int b)
{
    return a + b;
}
```

```
add2:
    leal    (%rdi,%rsi), %eax
    ret
```

```
int add3(int a, int b, int c)
{
    int r = add2(a, b);
    r = r + c;
    return r;
}
```

```
add3:
    pushq   %rbx
    movl    %edx, %ebx
    movl    $0, %eax
    call    add2
    addl    %ebx, %eax
    popq   %rbx
    ret
```

Registers

First 6 Arguments: %rdi, %rsi, %rdx, %rcx, %r8, %9

Return value: %rax

Example

```
int add2(int a, int b)
{
    return a + b;
}
```

```
int add3(int a, int b, int c)
{
    int r = add2(a, b);
    r = r + c;
    return r;
}
```

```
add2:
    leal    (%rdi,%rsi), %eax
    ret
```

```
add3:
    pushq  %rbx
    movl   %edx, %ebx
    movl   $0, %eax
    call  add2
    addl   %ebx, %eax
    popq  %rbx # restore %rbx before ret
    ret
```

save %rbx (callee-save)
before writing it

r is saved to %ebx

Registers

First 6 Arguments: %rdi, %rsi, %rdx, %rcx, %r8, %9

Return value: %rax

Quiz I

